## Active Filters with Complex Poles

## Complex Poles, No Zeros



To find the transfer function, write the voltage node equations

$$
V_{1}=V_{2}
$$

$$
\left(\frac{V_{1}}{R_{2}}\right)+\left(\frac{V_{1}-Y}{R_{1}}\right)=0
$$

$$
\left(\frac{V_{2}-X}{R}\right)+\left(\frac{V_{2}-V_{3}}{R}\right)+\left(\frac{V_{2}-Y}{1 / C s}\right)=0 \quad \text { node equation at } \mathrm{V} 2
$$

$$
\left(\frac{V_{3}-V_{2}}{R}\right)+\left(\frac{V_{3}}{1 / C s}\right)=0 \quad \text { node equation at } \mathrm{V} 3
$$

Solving (about 40 minutes later) you get

$$
Y=\left(\frac{k \cdot\left(\frac{1}{R C}\right)^{2}}{s^{2}+\left(\frac{3-k}{R C}\right) s+\left(\frac{1}{R C}\right)^{2}}\right) X
$$

where

$$
k=1+\frac{R_{1}}{R_{2}}
$$

This filter has two complex poles with

- Amplitude $=\frac{1}{R C}$
- Angle:

$$
3-k=2 \cos \theta
$$

- DC gain $k=\left(1+\frac{R_{2}}{R_{1}}\right)$

Note that the angle of the poles goes from

- 0 degrees when $\mathrm{k}=1$
- 90 degrees when $\mathrm{k}=3$ (an oscillator)


Example: 3rd Order LPF. Design a circuit to implement

$$
Y=\left(\frac{1,244,485}{(s+85)\left(s+121 \angle 69.5^{0}\right)\left(s+121 \angle-69.5^{0}\right)}\right) X
$$

Rewrite this as

$$
Y=\left(\frac{85}{s+85}\right)\left(\frac{14,641}{\left(s+121 \angle 69.5^{0}\right)\left(s+121 \angle-69.5^{0}\right)}\right) X
$$

Use the previous filters


To avoid loading, let

- $\mathrm{R} 0=10 \mathrm{k}$
- $\mathrm{R}=100 \mathrm{k}$

Matching terms in the denominator:

$$
\begin{array}{ll}
\left(\frac{1}{R_{0} C_{0}}\right)=85 & C_{0}=1.17 \mu F \\
\left(\frac{1}{R C}\right)=121 & C=0.082 \mu F \\
3-k=2 \cos \left(69.5^{0}\right) & \\
k=2.3 \\
1+\frac{R_{2}}{R_{1}}=2.3 & \\
\mathrm{R} 1=100 \mathrm{k}, \quad \mathrm{R} 2=1.3 \mathrm{k} &
\end{array}
$$

Note: This circuit has a DC gain of 2.3 (instead of 1.0).

- Option 1: Call the output 2.3Y
- Option 2: Reduce the gain by 2.3 x to bring the DC gain back to 1.00

The former solution is usually the better solution. Presumably, your circuit will need some gain anyway - this filer provides 2.3 x of the gain. The remaining gain comes from some other circuit.
The latter solution is usually better on tests where you want to answer the problem exactly to get full credit.

To attenuate the gain, use a Thevenin equivalent:


To find Ra and Rb :

$$
\begin{aligned}
& R_{a} \| R_{b}=10 k \\
& \left(\frac{R_{a} R_{b}}{R_{a}+R_{b}}\right)=10 k
\end{aligned}
$$

and

$$
\left(\frac{R_{a}}{R_{a}+R_{b}}\right) X=0.4348 X
$$

Solving

$$
\begin{aligned}
& R_{b}=\left(\frac{1}{0.4348}\right) 10 k=23 k \\
& R_{a}=17.69 k
\end{aligned}
$$

making the final circuit:


Complex Poles, One Zeros at s=0: $Y=\left(\frac{a s}{s^{2}+b s+c}\right) X$


To derive this transfer function, write the voltage node equations

$$
\begin{array}{lc}
V_{B}=0 & \text { node equation at } \mathrm{Y} \\
\left(\frac{V_{A}-X}{R_{1}}\right)+\left(\frac{V_{A}}{R_{2}}\right)+\left(\frac{V_{A}-V_{B}}{1 / C s}\right)+\left(\frac{V_{A}-Y}{1 / C s}\right)=0 & \text { node equation at A } \\
\left(\frac{V_{B}-V_{A}}{1 / C s}\right)+\left(\frac{V_{B}-Y}{R_{3}}\right)=0 & \text { node equation at B }
\end{array}
$$

Solving ( about 40 minutes later ) gives

$$
Y=\left(\frac{-\left(\frac{1}{R_{1} C}\right) s}{s^{2}+\left(\frac{2}{R_{3} C}\right) s+\left(\frac{R_{1}+R_{2}}{R_{1} R_{2}}\right)\left(\frac{1}{R_{3} C^{2}}\right)}\right) X
$$

Example: Design a filter to implement

$$
Y=\left(\frac{4 s}{s^{2}+2 s+200}\right) X
$$

Solution: There are 3 constraints and 4 degrees of freedom. Something is arbitrary, so let

$$
C=1 \mu F
$$

Now match terms

$$
\left(\frac{1}{R_{1} C}\right)=4 \quad \mathrm{R} 1=250 \mathrm{k}
$$

$$
\begin{array}{ll}
\left(\frac{2}{R_{3} C}\right)=2 & \mathrm{R} 3=1 \mathrm{M} \\
\left(\frac{R_{1}+R_{2}}{R_{1} R_{2}}\right)\left(\frac{1}{R_{3} C^{2}}\right)=200 & \\
\left(\frac{R_{1} R_{2}}{R_{1}+R_{2}}\right)=R_{1} \| R_{2}=\left(\frac{1}{200 R_{3} C^{2}}\right) & \\
R_{1} \| R_{2}=5 k & \mathrm{R} 2=5102
\end{array}
$$

