

## ECE 321 - Homework #3

1) Give the transfer function for a low-pass filter which meets the following design requirements:

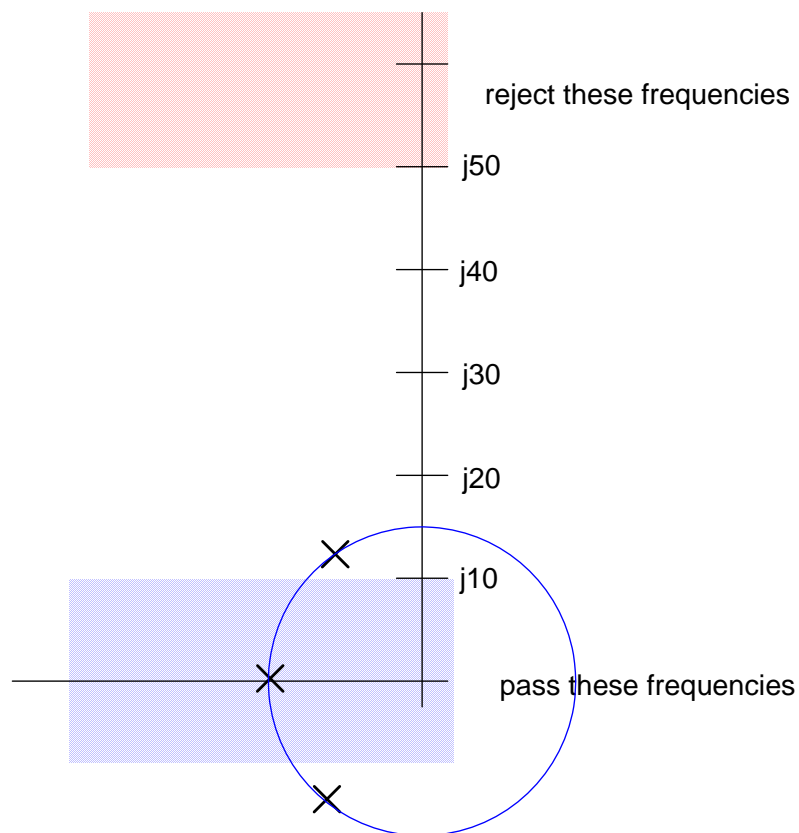
- Gain  $> 0.9$        $0 < \omega < 10$  rad/sec
- Gain  $< 0.1$        $\omega > 50$  rad/sec

There are many solutions.

Guess a 3rd-order low pass (because it isn't that hard to build: only needs one op-amp).

Pick a corner frequency between 10 and 50. Let the corner be 15 rad/sec.

Guess a Butterworth filter because they work well and are easy to compute.



After some trial and error with the corner, one solution is

$$G = \left( \frac{15^3}{(s+15)(s+15\angle 60^\circ)(s+15\angle -60^\circ)} \right)$$

Checking the gain at 10 and 50 rad/sec:

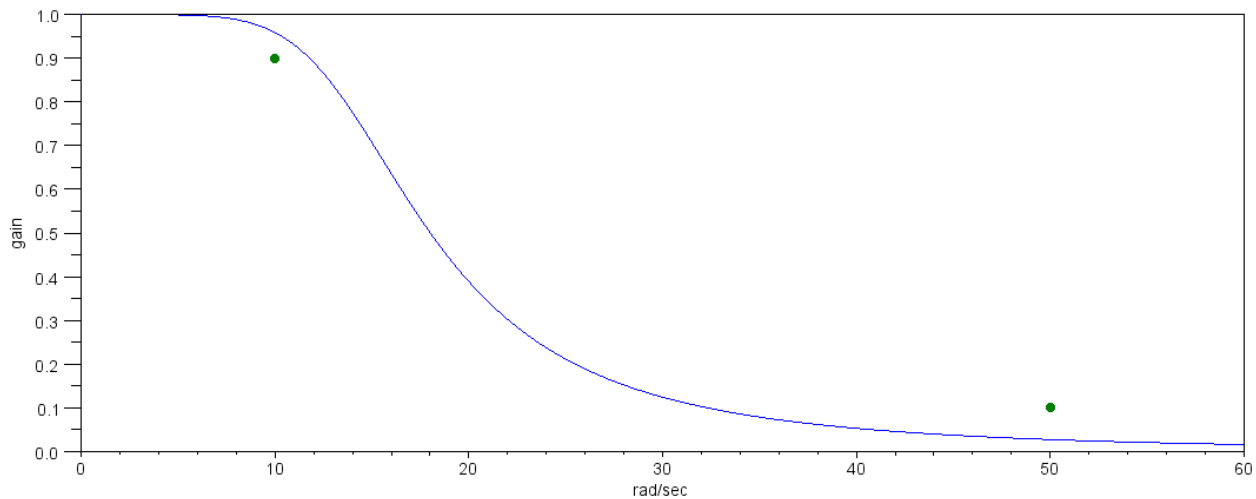
	Gain	Requirement	Requirement Met?
10 rad/sec	0.9587	> 0.9	yes
50 rad/sec	0.0269	< 0.1	yes

2) Plot the gain vs. frequency for your filter (actually, this is what I did first)

```
-->p1 = -15;
-->p2 = -15*exp(j*pi/3)
-->p3 = -15*exp(-j*pi/3)

-->G = 15^3 ./ ( (s-p1).*(s-p2).*(s-p3) );

-->plot(w,abs(G),[10,50],[0.9,0.1],'.');
-->xlabel('rad/sec');
-->ylabel('gain');
```



$$G = \left( \frac{15^3}{(s+15)(s+15\angle 60^\circ)(s+15\angle -60^\circ)} \right)$$

Note

- This filter meets the design requirements
- There is room for slop. You can adjust the corner (shift the curve left and right) and still meet the design requirements.

3) Design an op-amp circuit to implement the filter you chose.

The following circuit has the transfer function

$$Y = \left( \frac{k \left( \frac{1}{RC} \right)^3}{\left( s + \frac{1}{RC} \right) \left( s^2 + \left( \frac{3-k}{RC} \right) s + \left( \frac{1}{RC} \right)^2 \right)} \right) X \quad k = 1 + \frac{R_2}{R_1}$$

This should be

$$\left( \frac{15^3}{(s+15)(s+15\angle 60^\circ)(s+15\angle -60^\circ)} \right) = \left( \frac{15^3}{(s+15)(s^2+15s+225)} \right)$$

Matching terms

$$\left( \frac{1}{RC} \right) = 15$$

$$R = 1\text{M}, \quad C = 1/15 \text{ uF}$$

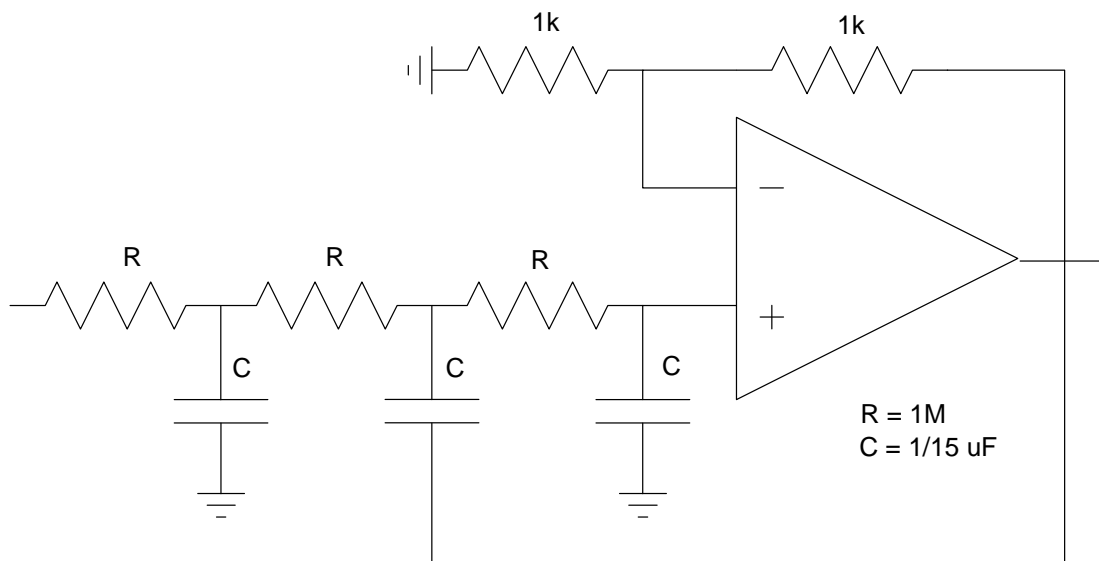
$$\left( \frac{3-k}{RC} \right) = 15$$

$$3 - k = 1$$

$$k = 2$$

The actual gain is twice what it should be. Normally you don't worry about this: you usually need to amplify the signal. The filter provides a gain of two. The rest comes from the rest of the circuit.

$$Y = \left( \frac{2 \cdot 15^3}{(s+15)(s+15\angle 60^\circ)(s+15\angle -60^\circ)} \right) X$$



4) Give the transfer function for a low-pass filter which meets the following design criteria:

- Gain > 0.9       $\omega = 10$  rad/sec
- Gain < 0.1       $\omega < 5$  rad/sec      or       $\omega > 15$  rad/sec

Let's make the bandwidth 10 rad/sec +/- 1 rad/sec

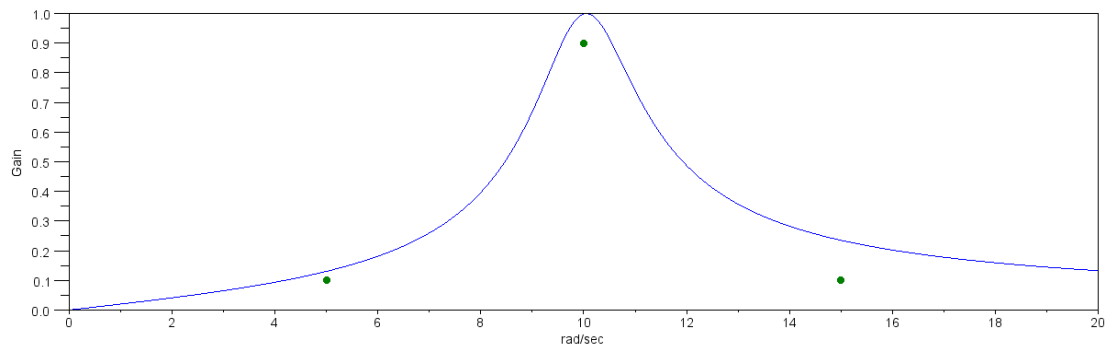
- The poles are centered at  $j10$
- They are one away from  $j10$

```
-->w = [0:0.01:20]';
-->j = sqrt(-1);
-->s = j*w;

-->p1 = 1 + j*10;
-->p2 = conj(p1);
-->G = s ./ ( (s+p1) .* (s+p2) );
```

The peak gain is off, so adjust G(s) so that the max is one:

```
-->G = G / max(abs(G));
-->plot(w,abs(G),[5,10,15],[0.1,0.9,0.1],'.');
```



The gain is too high at 5 and 15, so slide the pole in (reduce the real part from -1 to -0.4) to make it more selective. After some trial and error,

```
-->p1 = 0.4 + j*10;
-->p2 = conj(p1);
-->G = s ./ ( (s+p1) .* (s+p2) );
-->G = G / max(abs(G));

-->plot(w,abs(G),[5,10,15],[0.1,0.9,0.1],'.');
-->xlabel('rad/sec');
-->ylabel('Gain');
```

This works, so

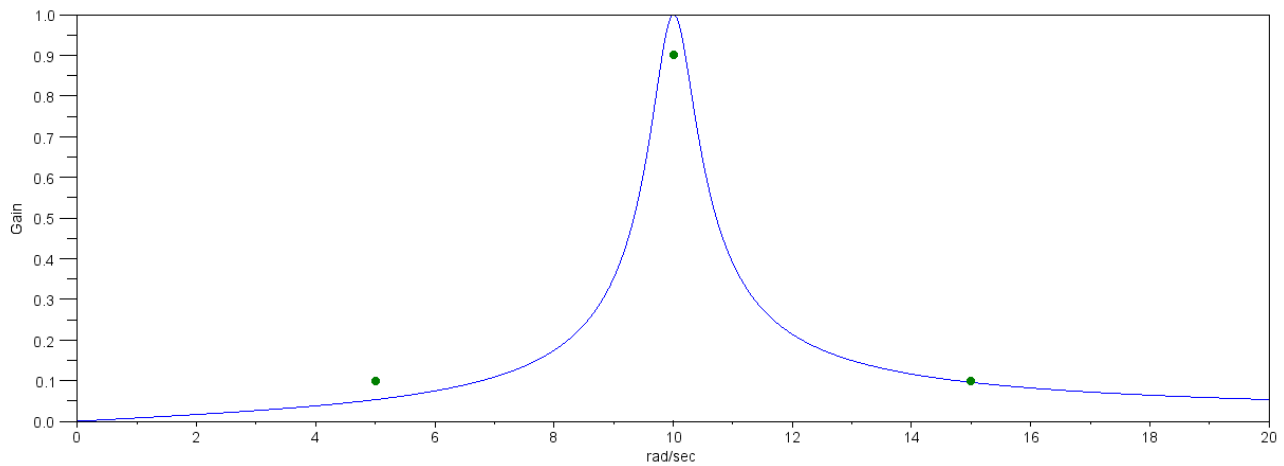
$$Y = \left( \frac{0.8s}{(s+0.4+j10)(s+0.4-j10)} \right) X$$

Checking the gain at 5, 10, and 15 rad/sec

```
-->s = j*5;  
-->abs( 0.8*s ./ ( (s+p1) .* (s+p2) ) )  
  
0.0531446  
  
-->s = j*10;  
-->abs( 0.8*s ./ ( (s+p1) .* (s+p2) ) )  
  
0.9998001  
  
-->s = j*15;  
-->abs( 0.8*s ./ ( (s+p1) .* (s+p2) ) )  
  
0.0956820
```

	Gain	Requirement	Requirement Met?
5 rad/sec	0.0531	< 0.1	yes
10 rad/sec	0.9998	> 0.9	yes
15 rad/sec	0.0956	< 0.1	yes

5) Plot the gain vs. Frequency



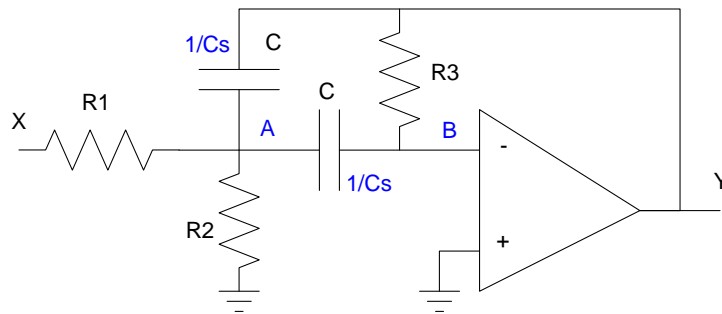
Gain vs. Frequency for Problem 5:  
The gain is less than 0.1 at 5 and 15 rad/sec, more than 0.9 at 10 rad/sec

6) Design a filter to implement this transfer function

$$Y = \left( \frac{0.8s}{(s+0.4+j10)(s+0.4-j10)} \right) X$$

$$Y = \left( \frac{0.8s}{s^2+0.8s+100.16} \right) X$$

A filter of this form (zero at  $s = 0$ , two poles) can be implemented with the following circuit:



$$Y = \left( \frac{-\left(\frac{1}{R_1 C}\right)s}{s^2 + \left(\frac{2}{R_3 C}\right)s + \left(\frac{R_1 + R_2}{R_1 R_2}\right)\left(\frac{1}{R_3 C^2}\right)} \right) X$$

Matching terms:

Let  $C_1 = C_2 = 1\mu\text{F}$

$$\left(\frac{1}{R_1 C}\right) = 0.8 \quad R_1 = 1.25\text{M}$$

$$\left(\frac{2}{R_3 C}\right) = 0.8 \quad R_3 = 2.5\text{M}$$

$$\left(\frac{R_1 + R_2}{R_1 R_2}\right)\left(\frac{1}{R_3 C^2}\right) = 100.16 \quad R_2 = 4.06\text{k}$$