ECE 376 - Final Exam: Name __

Open-Book, Open Note, Calculators and Matlab permitted. Individual Effort.

- 1) Binary Outputs: Assume a 6411 NPN transistor (if needed)
 - Vbe = 0.7V
 - Vce(sat) = 0.2V
 - $\beta = 300$
 - max(Ic) = 6A
- 1a) Give a circuit which allows a PIC to turn on and off a 40mW LED at 2mA
 - Id = 20mA
 - Vd = 2.0V

- 1b) Give a circuit which allows a PIC to turn on and off 12V DC motor, which draws up to 3A @ 12V
 - V(motor) = 12V
 - Current draw < 3A

2) Analog Inputs: A CdS light sensor has the following resistance

- lux (light intensity) relationship

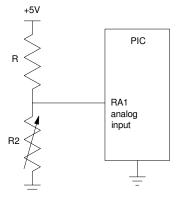
$$R_2 = 1000 \cdot \left(\frac{10}{Lux}\right)^{0.6} \text{ Ohms}$$

If the A/D reading is 417, determine

- The voltage,
- · The resistance,
- The light level in Lux, and
- The resolution (the smallest change in Lux you can detect)

with the following circuit. Assume

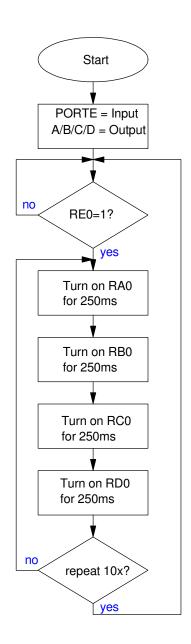
• R = 900 + 100*(your birth month) + (your birth date)



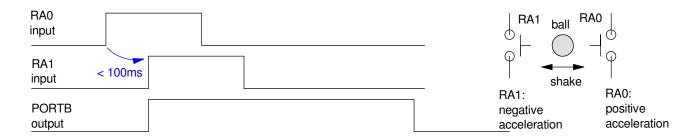
R 900 + 100*mo + day	A/D reading 01023	Voltage A/D = 712	R A/D = 712	Resolution smallest change in Lux you can measure
	712			

- 3) C-Coding **without** interrupts: Write a C program for driving Christmas tree lights. Assume each output pin is connected to an LED. When pin RE0 goes high, the LEDs are to be turned on one at a time in the following sequence
- RA0 RB0 RC0 RD0 repeat ten times with a 250ms delay between each light. Write the corresponding C code

```
void main(void) {
   ADCON1 = 0x0F;
```



- 4) C Coding without interrupts: Christmas Present: Write a C program that turns on lights if the PIC is shaken back and forth in less than 100ms.
 - RA0: 5V if the PIC board experiences positive acceleration
 - RA1: 5V if the PIC board experiences negative acceneration
 - PORTB: Connected to eight LEDs



```
void main(void) {
   ADCON1 = 0x0F;
```

5) C-Coding **with** interrupts: Write a C which uses interrupts to turn on the lighs for a Christmas tree:

- When pin RB0 goes high (INT0 interrupt)
- Pins RA0, RA1, RA2, then RA3 go high sequentially
- Each pin goes high for 100ms (controlled by Timer0 interrupt)
- Once RA3 turns off, the process stops until the next INTO interrupt

RB0 (input)		
RA0 (output) 100ms		
RA1 (output) 100ms		
RA2 (output)	100ms	
RA3 (output)		100ms

INTO initialization rising or falling edge	Timer0 Initialization Pre-scalar = ?	

INTO Interrupt Service Routine start the light show when RB0 goes high

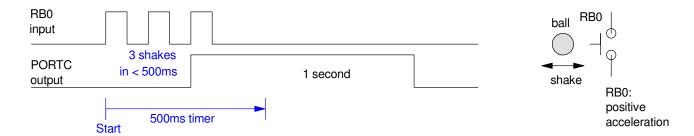
Timer0 Interrupt Service Routine
Trigger every 100ms
Turn on RA0 then RA1 then RA2 then RA3
three times then stop (until next INT0 iinterrupt)

if(INTOIF) {

if(TMR1IF) {

6) C-Coding **with** interrupts. Write a C program which uses interrupts to detect if a Christmas present is being shaken.

- If RB0 goes high three times in less than 500ms
- PORTC goes high (0xFF) for one second



INT0	Timer2	Timer2	Timer2	Timer2
rising / falling edge	N for 1ms		B	C

Main Loop if needed	$INTO\ Interrupt \\ Count\ edges \\ On\ 1st\ edge,\ start\ 500ms\ counter \\ If\ 3\ edges\ in\ < 500ms,\ turn\ on\ PORTC\ for\ 1sec$	Timer2 every 1ms
	if (INTOIF) {	if(TMR2IF) {