ECE 376 - Homework #11

z-Transforms and Digital Filters. Due Wednesday, April 20th

1) Assume X and Y are related by the following transfer function

$$Y = \left(\frac{10(s+3)}{(s+2)(s+7)}\right)X$$

a) What is the differential equation relating X and Y?

cross multiply

$$(s^2 + 9s + 14)Y = (10s + 30)X$$

'sy' means 'the derivative of Y

$$\frac{d^2y}{dt^2} + 9\frac{dy}{dt} + 14y = 10\frac{dx}{dt} + 30x$$
$$y'' + 9y' + 14y = 10x' + 30x$$

b) Find y(t) assuming

$$x(t) = 2 + 4\sin(5t)$$

Use superposition treating this as two separate problems (one at each frequency)

(i)
$$x(t) = 2$$
$$s = 0$$
$$Y = \left(\frac{10(s+3)}{(s+2)(s+7)}\right)_{s=0} \cdot (2)$$
$$Y = 4.286$$

(ii)
$$x(t) = 4\sin(5t)$$

 $X = 0 - j4$ real = cosine, imag = - sine
 $s = j5$
 $Y = \left(\frac{10(s+3)}{(s+2)(s+7)}\right)_{s=j5} \cdot (0 - j4)$
 $Y = -3.541 - j3.579$
 $y(t) = -3.541\cos(5t) + 3.579\sin(5t)$

The total answer is then DC + AC

 $y(t) = 4.286 - 3.541\cos(5t) + 3.579\sin(5t)$

2) Assume X and Y are related by the following transfer function

$$Y = \left(\frac{0.01(z+1)}{(z-0.98)(z-0.92)}\right)X$$

a) What is the difference equation relating X and Y?

cross multiply and multipy out

$$(z^2 - 1.9z + 0.9016)Y = 0.01(z + 1)X$$

'zY' means 'y(k+1)' or 'the next value of y'

$$y(k+2) - 1.9y(k+1) + 0.9016y(k) = 0.01(x(k+1) + x(k))$$

with a change in variable, you could also write this as (either is correct)

$$y(k) - 1.9y(k-1) + 0.9016y(k-2) = 0.01(x(k-1) + x(k-2))$$

b) Find y(t) assuming a sampling rate of T = 0.01 second

$$x(t) = 2 + 4\sin(5t)$$

Use superposition and treat this as two separate problems

i)
$$x(t) = 2$$

 $s = 0$
 $z = e^{sT} = 1$
 $Y = \left(\frac{0.01(z+1)}{(z-0.98)(z-0.92)}\right)_{z=1} \cdot (2) = 25$

ii)
$$x(t) = 4\sin(5t)$$

 $X = 0 - j4$ real = cosine, imag = -sine
 $s = j5$
 $z = e^{sT} = 1 \angle 0.05 rad = 1 \angle 2.86^{0}$
 $Y = \left(\frac{0.01(z+1)}{(z-0.98)(z-0.92)}\right)_{z=1 \angle 2.86^{0}} \cdot (0 - j4) = -15.799 + j2.901$
 $y(t) = -15.799\cos(5t) - 2.901\sin(5t)$

The total answer is DC + AC

 $y(t) = 25 - 15.799\cos(5t) - 2.901\sin(5t)$

Problem 3) Assume G(s) is a low-pass filter with real poles:

$$G(s) = \left(\frac{90}{(s+2)(s+4)(s+10)}\right)$$

Design a digital filter, G(z), which has approximately the same gain vs. frequency as G(s). Assume a sampling rate of T = 0.01 second.

$$s = -2$$

 $s = -4$
 $z = e^{sT} = 0.9802$
 $z = e^{sT} = 0.9608$
 $z = e^{sT} = 0.9048$

The form of G(z) is then

$$G(z) = \left(\frac{k}{(z - 0.9802)(z - 0.9608)(z - 0.9048)}\right)$$

To find k, match the DC gain

$$\left(\frac{90}{(s+2)(s+4)(s+10)}\right)_{s=0} = 1.25$$
$$\left(\frac{k}{(z-0.9802)(z-0.9608)(z-0.9048)}\right)_{z=1} = 1.25$$
$$k = 0.000092358$$

so

$$G(z) = \left(\frac{9.2358 \cdot 10^{-5}}{(z - 0.9802)(z - 0.9608)(z - 0.9048)}\right)$$

Plot the gain vs. frequency for both filters from 0 to 50 rad/sec.

In Matlab

```
>> T = 0.01;
>> w = [0:0.01:30]';
>> s = j*w;
>> Z = exp(s*T);
>> Gs = 90 ./ ( (s+2).*(s+4).*(s+10) );
>> % z-plane
>> p1 = exp(-2*T)
p1 = 0.9802
>> p2 = exp(-4*T)
p2 = 0.9608
>> p3 = exp(-10*T)
p3 = 0.9048
>> Gz = 1 ./ ( (z-p1).*(z-p2).*(z-p3) );
```

```
>> max(abs(Gs))
ans = 1.1250
>> max(abs(Gz))
ans = 1.3534e+004
>> k = max(abs(Gs)) / max(abs(Gz))
k = 8.3122e-005
>> Gz = k ./ ( (z-p1).*(z-p2).*(z-p3) );
>> plot(w,abs(Gs),'b',w,abs(Gz),'r')
>> xlabel('Frequency (rad/sec)');
```





Problem 4) Assume G(s) is the following band-pass filter:

$$G(s) = \left(\frac{6s}{(s+1+j16)(s+1-j16)}\right)$$

Design a digital filter, G(z), which has approximately the same gain vs. frequency as G(s). Assume a sampling rate of T = 0.01 second.

zero

$$s = 0 \qquad \qquad z = e^{sT} = 1$$

poles

$$s = -1 + j16$$

 $s = -1 - j16$
 $z = e^{sT} = 0.9774 + j0.1577$
 $z = e^{sT} = 0.9744 - j0.1577$

meaning

$$G(z) = \left(\frac{k(z-1)}{(z-0.9744+j0.1577)(z-0.9744-j0.1577)}\right)$$

To find k, match the maximum gain vs. frequency (from Matlab)

$$G(z) = \left(\frac{0.0099(z-1)}{(z-0.9744+j0.1577)(z-0.9744-j0.1577)}\right)$$

In Matlab

```
>> T = 0.01;
>> z1 = exp(0*T)
z1 =
       1
>> p1 = \exp((-1+j*16)*T)
p1 = 0.9774 + 0.1577i
>> p2 = exp((-1-j*16)*T)
p2 = 0.9774 - 0.1577i
>> w = [0:0.01:30]';
>> s = j*w;
>> z = \exp(s^{T});
>>
>> Gs = 6*s ./ ( (s+1+j*16).*(s+1-j*16) );
>> Gz = 6*(z-z1) ./ ( (z-p1).*(z-p2) );
>> k = max(abs(Gs)) / max(abs(Gz))
k =
       0.0099
>> Gz = k * 6*(z-z1) ./ ( (z-p1).*(z-p2) );
>> plot(w,abs(Gs),'b',w,abs(Gz),'r')
```

Plot the gain vs. frequency for both filters from 0 to 50 rad/sec.



Problem 5) Write a C program to implement the digital filter, G(z)

$$G(z) = \left(\frac{0.0099(z-1)}{(z-0.9744+j0.1577)(z-0.9744-j0.1577)}\right)$$

multiply out

>> poly([p1,p2]) ans = 1.0000 -1.9548 0.9802

$$G(z) = \left(\frac{0.0099(z-1)}{\left(z^2 - 1.9548x + 0.9802\right)}\right)$$

In C:

```
while(1) {
    x2 = x1;
    x1 = x0;
    x0 = A2D_Read(0);
    y2 = y1;
    y1 = y0;
    y0 = 1.9548*y1 - 0.9802*y2 + 0.0099*(x1 - x2);
    D2A(y0);
    Wait_ms(10);
    }
```