

# Homework #7: ECE 461/661

Error Constants, Routh Criteria, Sketching a Root Locus. Due Monday, October 15, 2018

## Error Constants:

1) Fill in the following table\

Open-Loop System G(s)	Type 0 - 1 - 2	Kp	Kv	Steady-State Error for a Step Input
$\left(\frac{20}{(s+2)(s+5)}\right)$				
$\left(\frac{20}{(s-2)(s+5)}\right)$				
$\left(\frac{20}{s(s+2)(s+5)}\right)$				
$\left(\frac{20(s+1)}{s^2(s+2)(s+5)}\right)$				

## Routh Criteria

Using a Routh table, determine the range of K which results in a negative-definite polynomial (i.e. a stable closed-loop system)

- 2)  $(s + 2)(s + 5)(s + 10) + 2k = 0$
- 3)  $(s - 1)(s + 5)(s + 9)(s + 10) + 2k(s + 1) = 0$
- 4)  $s^2(s + 2)(s + 5) + 2k(s + 1) = 0$

## Sketching a Root Locus

Draw the root locus plot for the following systems (it's OK to use Matlab). Calculate and show on your plots

- The real-axis loci,
- The breakaway point(s),
- The  $j\omega$  crossing(s),
- The asymptotes, and
- The approach angles (if any)

5)  $G(s) = \left(\frac{2}{(s+2)(s+5)(s+10)}\right)$

6)  $G(s) = \left(\frac{2(s+1)}{(s-1)(s+5)(s+9)(s+10)}\right)$

7)  $G(s) = \left(\frac{2(s+j2)(s-j2)}{s(s+2)(s+5)(s+10)}\right)$

8)  $G(s) = \left(\frac{20}{s(s+2)(s+5)(s+10)}\right)$