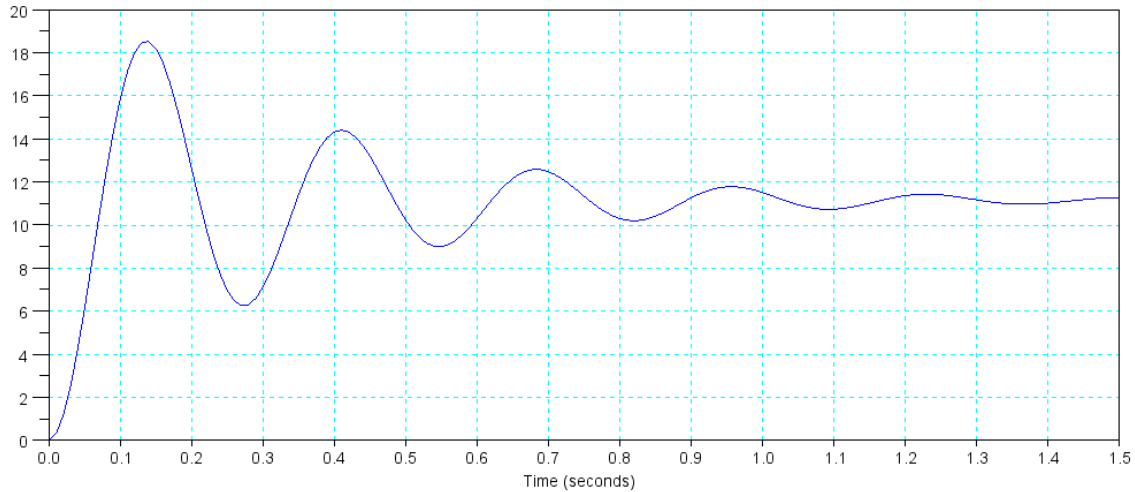


# ECE 461 - Final: Name \_\_\_\_\_

Fall - 2020

1a) Give the transfer function for a system with the following step response:

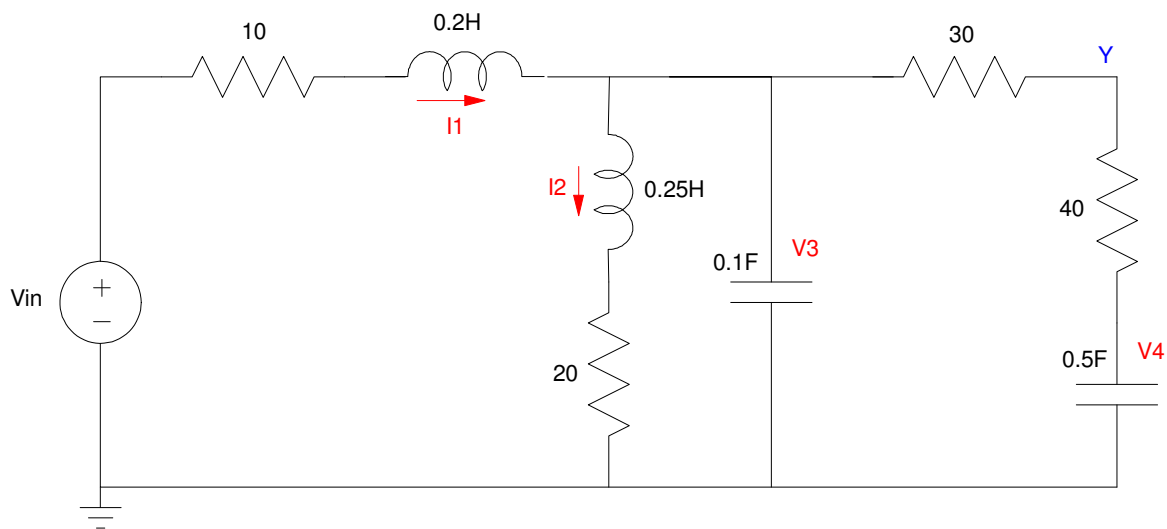


1b) What is the step response for the following system:

$$Y = \left( \frac{2000}{(s+7+j12)(s+7-j12)(s+40)} \right) X$$

| DC Gain | 2% Settling Time | % Overshoot |
|---------|------------------|-------------|
|         |                  |             |

2a) Write the differential equations which describe the following circuit (i.e. write the N differential equations which correspond to the voltage node equations)



2b) Express these dynamics in state-space form

$$s \begin{bmatrix} I_1 \\ I_2 \\ V_3 \\ V_4 \end{bmatrix} = \begin{bmatrix} - & - & - & - \\ - & - & - & - \\ - & - & - & - \\ - & - & - & - \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ V_3 \\ V_4 \end{bmatrix} + \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} V_{in}$$

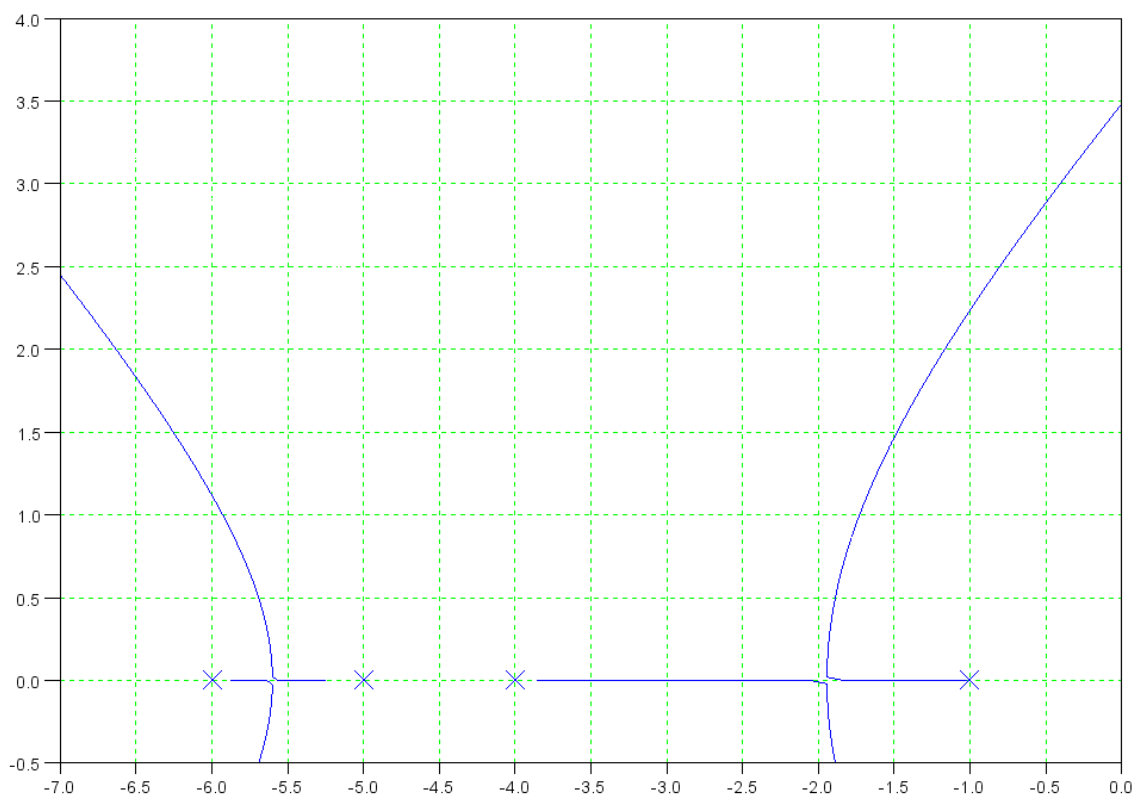
$$Y = \begin{bmatrix} - & - & - & - \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ V_3 \\ V_4 \end{bmatrix}$$

3) Gain Compensation: The root locus for

$$G(s) = \left( \frac{40}{(s+1)(s+4)(s+5)(s+6)} \right)$$

is shown below. Determine the following:

|   |  |
|---|--|
| Maximum gain, k, for a stable closed-loop system        |  |
| k for a damping ratio of 0.6                            |  |
| Closed-loop dominant pole(s) for a damping ratio of 0.6 |  |
| Closed-Loop DC gain for a damping ratio of 0.6          |  |



4) Given the following stable system

$$G(s) = \left( \frac{100}{(s+0.5)(s+2)(s+6)} \right)$$

Determine a compensator,  $K(s)$ , which results in the closed-loop system having

- No error for a step input, and
- A closed-loop dominant pole at  $s = -2 + j5$

5) Given the following stable system

$$G(s) = \left( \frac{100}{(s+0.5)(s+2)(s+6)} \right)$$

Determine a digital compensator,  $K(z)$ , which results in the closed-loop system having

- No error for a step input,
- A closed-loop dominant pole at  $s = -2 + j5$ , and
- A sampling rate of  $T = 0.2$

6) Given the following stable system

$$G(s) = \left( \frac{100}{(s+0.5)(s+2)(s+6)} \right)$$

Determine a digital compensator,  $K(z)$ , which results in the closed-loop system having

- A closed-loop DC gain of 1.000 (i.e. no error for a step input),
- A 0dB gain frequency of 5 rad/sec, and
- $M_m = 1.45$

7) Determine R and C so that the following compensator has the transfer function of

$$K(s) = 300 \left( \frac{(s+2)(s+9)}{s(s+15)} \right)$$

