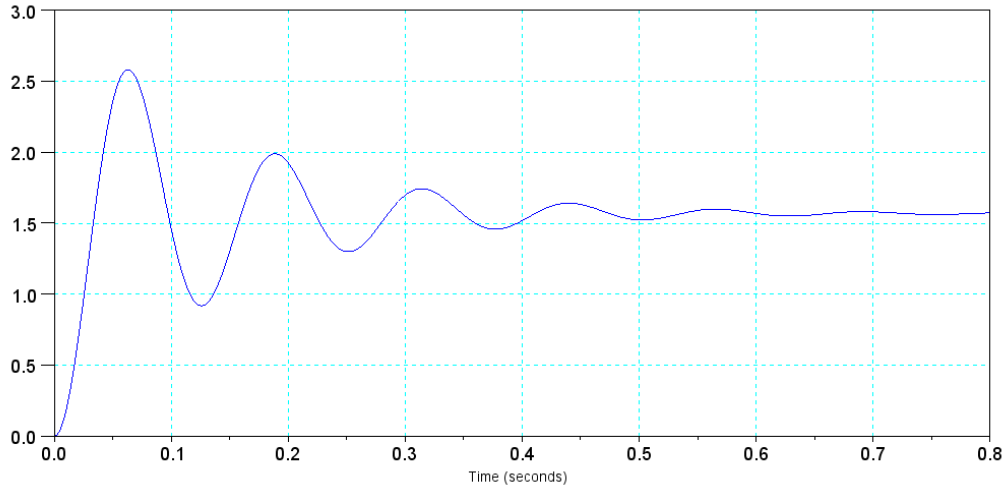


# ECE 461 - Final: Name \_\_\_\_\_

Fall - 2021

1a) Give the transfer function for a system with the following step response:

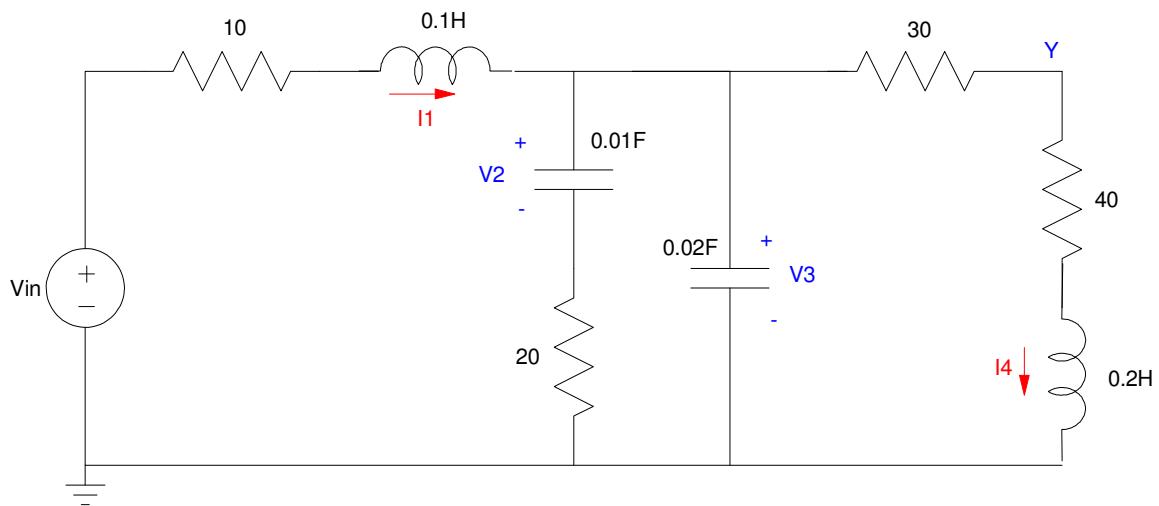


1b) What is the step response for the following system:

$$Y = \left( \frac{20,000}{(s+12+j30)(s+12-j30)(s+140)} \right) X$$

DC Gain	2% Settling Time	% Overshoot

2a) Write the differential equations which describe the following circuit (i.e. write the N differential equations which correspond to the voltage node equations)



2b) Express these dynamics in state-space form

$$s \begin{bmatrix} I_1 \\ V_2 \\ V_3 \\ I_4 \end{bmatrix} = \begin{bmatrix} - & - & - & - \\ - & - & - & - \\ - & - & - & - \\ - & - & - & - \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \\ V_3 \\ I_4 \end{bmatrix} + \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} V_{in}$$

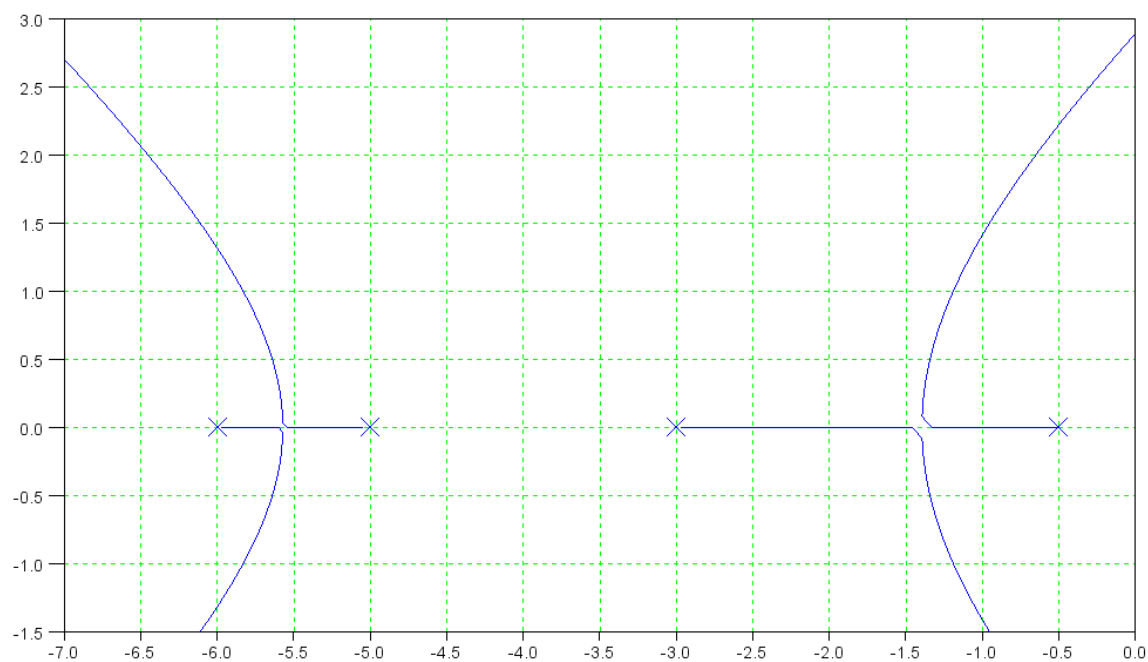
$$Y = \begin{bmatrix} - & - & - & - \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \\ V_3 \\ I_4 \end{bmatrix}$$

3) Gain Compensation: The root locus for

$$G(s) = \left( \frac{40}{(s+0.5)(s+3)(s+5)(s+6)} \right)$$

is shown below. Determine the following:

Maximum gain, k, for a stable closed-loop system	
k for a damping ratio of 0.4	
Closed-loop dominant pole(s) for a damping ratio of 0.4	
Closed-Loop DC gain for a damping ratio of 0.4	



4) Given the following stable system

$$G(s) = \left( \frac{40}{(s+0.5)(s+3)(s+5)(s+6)} \right)$$

Determine a compensator,  $K(s)$ , which results in the closed-loop system having

- No error for a step input, and
- A closed-loop dominant pole at  $s = -1.5 + j4$

5) Given the following stable system

$$G(s) = \left( \frac{40}{(s+0.5)(s+3)(s+5)(s+6)} \right)$$

Determine a digital compensator,  $K(z)$ , which results in the closed-loop system having

- No error for a step input,
- A closed-loop dominant pole at  $s = -1.5 + j7$ , and
- A sampling rate of  $T = 0.1$

6) Given the following stable system

$$G(s) = \left( \frac{40}{(s+0.5)(s+3)(s+5)(s+6)} \right)$$

Determine a compensator,  $K(s)$ , which results in the closed-loop system having

- A closed-loop DC gain of 1.000 (i.e. no error for a step input),
- A 0dB gain frequency of 7 rad/sec, and
- A phase margin of 24 degrees

7) Determine R and C so that the following compensator has the transfer function of

$$K(s) = 300 \left( \frac{(s+2)(s+9)}{s(s+15)} \right)$$

