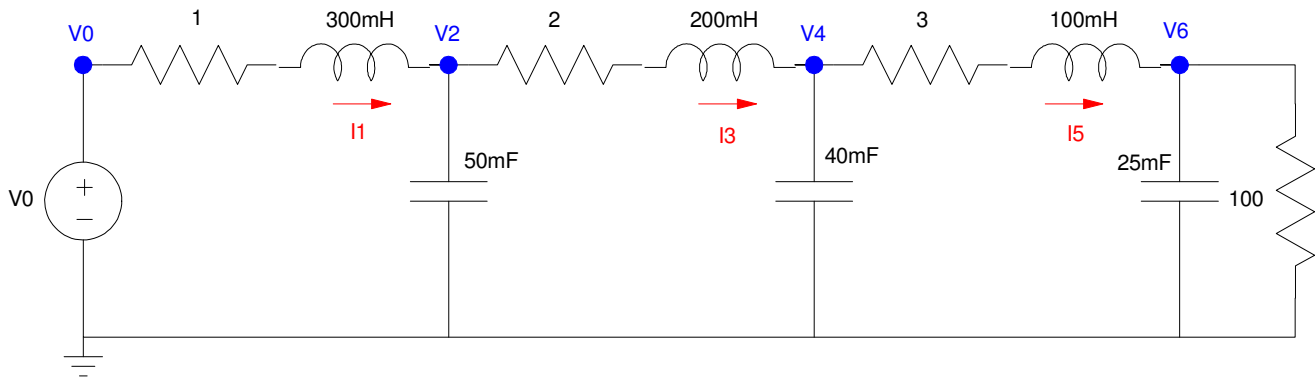


# ECE 463/663 - Homework #2

State-Space, Eigenvalues, Eigenvectors. Due Monday, Jan 23rd

1) For the following RLC circuit

Specify the dynamics for the system (write N coupled differential equations)



Inductors:  $V = L \frac{dI}{dt} = LsI$

$$V_1 = 0.3sI_1 = V_0 - I_1 - V_2$$

$$V_3 = 0.2sI_3 = V_2 - 2I_3 - V_4$$

$$V_5 = 0.1sI_5 = V_4 - 3I_5 - V_6$$

Capacitors:  $I = C \frac{dV}{dt} = CsV$

$$I_2 = 0.05sV_2 = I_1 - I_3$$

$$I_4 = 0.04sV_4 = I_3 - I_5$$

$$I_6 = 0.025sV_6 = I_5 - \left(\frac{V_6}{100}\right)$$

Plugging in numbers:

$$sI_1 = 3.33V_0 - 3.33I_1 - 3.33V_2$$

$$sV_2 = 20I_1 - 20I_3$$

$$sI_3 = 5V_2 - 10I_3 - 5V_4$$

$$sV_4 = 25I_3 - 25I_5$$

$$sI_5 = 10V_4 - 30I_5 - 10V_6$$

$$sV_6 = 40I_5 - 0.4V_6$$

Express these dynamics in state-space form

$$\begin{bmatrix} sI_1 \\ sV_2 \\ sI_3 \\ sV_4 \\ sI_5 \\ sV_6 \end{bmatrix} = \begin{bmatrix} -3.33 & -3.33 & 0 & 0 & 0 & 0 \\ 20 & 0 & -20 & 0 & 0 & 0 \\ 0 & 5 & -10 & -5 & 0 & 0 \\ 0 & 0 & 25 & 0 & -25 & 0 \\ 0 & 0 & 0 & 10 & -35 & -10 \\ 0 & 0 & 0 & 0 & 50 & -0.4 \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \\ I_3 \\ V_4 \\ I_5 \\ V_6 \end{bmatrix} + \begin{bmatrix} 3.33 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} V_0$$

$$Y = V_6 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} X$$

Determine the transfer function from Vin to V5

```
>> a1 = [-3.3333, -3.3333, 0, 0, 0, 0];
>> a2 = [20, 0, -20, 0, 0, 0];
>> a3 = [0, 5, -10, -5, 0, 0];
>> a4 = [0, 0, 25, 0, -25, 0];
>> a5 = [0, 0, 0, 10, -35, -10];
>> a6 = [0, 0, 0, 0, 50, -0.4];
>> A = [a1; a2; a3; a4; a5; a6]
```

```
-3.3333    -3.3333         0         0         0         0
20.0000         0   -20.0000         0         0         0
         0     5.0000   -10.0000   -5.0000         0         0
         0         0    25.0000         0   -25.0000         0
         0         0         0    10.0000   -35.0000   -10.0000
         0         0         0         0    50.0000   -0.4000
```

```
>> B = [3.3333; 0; 0; 0; 0; 0]
```

```
3.3333
 0
 0
 0
 0
 0
```

```
>> C = [0, 0, 0, 0, 0, 1];
>> D = 0;
>> G6 = ss(A, B, C, D);
```

```
>> zpk(G6)
```

**4166625**

-----  
**(s<sup>2</sup> + 5.573s + 27.64) (s<sup>2</sup> + 10.6s + 217) (s<sup>2</sup> + 32.56s + 730.7)**

```
>> P = eig(A)
```

```
-2.7863 + 4.4580i  
-2.7863 - 4.4580i  
-5.2981 +13.7465i  
-5.2981 -13.7465i  
-16.2822 +21.5785i  
-16.2822 -21.5785i
```

2) For the transfer function from V0 to V6

- Determine a 1st or 2nd-order approximation for this transfer function
- Plot the step response of the actual 6th-order system and its approximation

Keep the dominant pole(s)

```
-2.7863 + 4.4580i  
-2.7863 - 4.4580i
```

Match the DC gain

```
>> G2 = zpk([],P(1:2),1);  
>> k = evalfr(G6,0) / evalfr(G2,0)
```

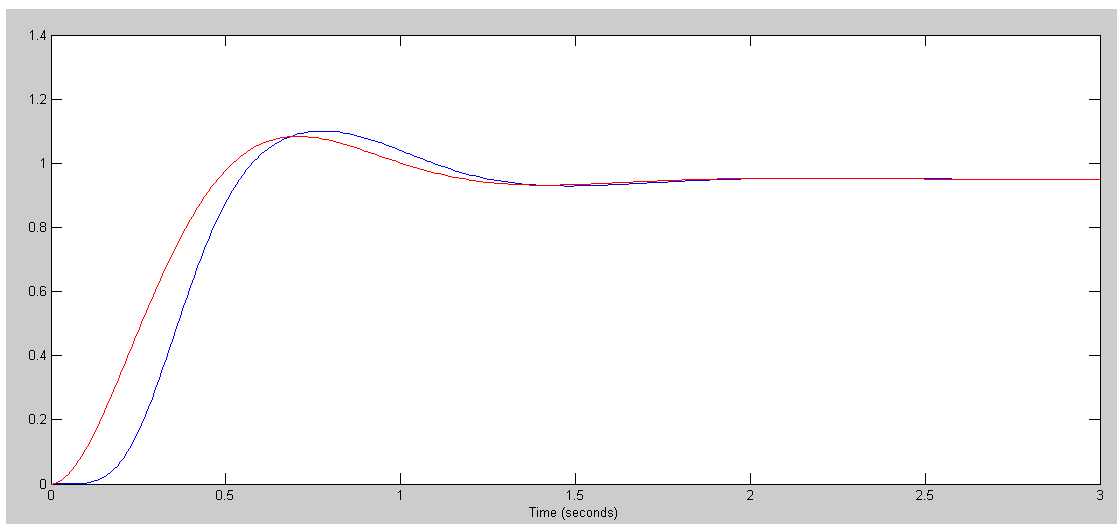
```
k = 26.2716
```

```
>> G2 = zpk([],P(1:2),k)
```

**26.2716**

-----  
**(s<sup>2</sup> + 5.573s + 27.64)**

```
>> t = [0:0.01:3]';  
>> y6 = step(G6,t);  
>> y2 = step(G2,t);  
>> plot(t,y6,'b',t,y2,'r');
```



6th Order System (blue) & 2nd-Order Approximation (red)

3) For this circuit...

- What initial condition will the energy in the system decay as slowly as possible?
- What initial condition will the energy in the system decay as fast as possible?

This is an eigvalue / eigenvector problem. The eigenvectors of A are:

```
>> [M,V] = eig(A)

slow
-0.2154 + 0.1523i -0.2154 - 0.1523i 0.0211 + 0.1479i 0.0211 - 0.1479i 0.0097 - 0.0039i 0.0097 + 0.0039i
0.2390 + 0.2630i 0.2390 - 0.2630i 0.6224 0.6224 0.0125 - 0.0775i 0.0125 + 0.0775i
-0.1234 + 0.1356i -0.1234 - 0.1356i 0.1860 - 0.2799i 0.1860 + 0.2799i -0.0638 - 0.0805i -0.0638 + 0.0805i
0.5380 + 0.1774i 0.5380 - 0.1774i -0.3220 - 0.2482i -0.3220 + 0.2482i -0.4150 + 0.0966i -0.4150 - 0.0966i
-0.0318 + 0.0595i -0.0318 - 0.0595i -0.0187 - 0.1554i -0.0187 + 0.1554i -0.2507 + 0.3406i -0.2507 - 0.3406i
0.6671 0.6671 -0.4801 + 0.2391i -0.4801 - 0.2391i 0.7892 0.7892

fast
-2.7863 - 4.4580i -2.7863 + 4.4580i -5.2981 -13.7465i -5.2981 +13.7465i -16.2822 -21.5785i -16.2822 +21.5785i

>>
```

The slow mode (blue) has initial conditions of

$$x(t) = x_0 e^{-2.7863t} \cos(4.4580t)$$

```
>> real(M(:,1))
```

```
I1 -0.2154
V2 0.2390
I3 -0.1234
V4 0.5380
I5 -0.0318
V6 0.6671
```

$$x(t) = x_0 e^{-2.7863t} \sin(4.4580t)$$

```
>> imag(M(:,1))
```

```
I1 0.1523
V2 0.2630
I3 0.1356
V4 0.1774
I5 0.0595
V6 0
```

The fast mode (red) has initial conditions of

$$x(t) = x_0 e^{-16.28t} \cos(21.58t)$$

```
>> real(M(:,6))
```

```
I1 0.0097
V2 0.0125
I3 -0.0638
V4 -0.4150
I5 -0.2507
V6 0.7892
```

$$x(t) = x_0 e^{-16.28t} \sin(21.58t)$$

```
>> imag(M(:,6))
```

```
I1 0.0039
V2 0.0775
I3 0.0805
V4 -0.0966
I5 -0.3406
V6 0
```

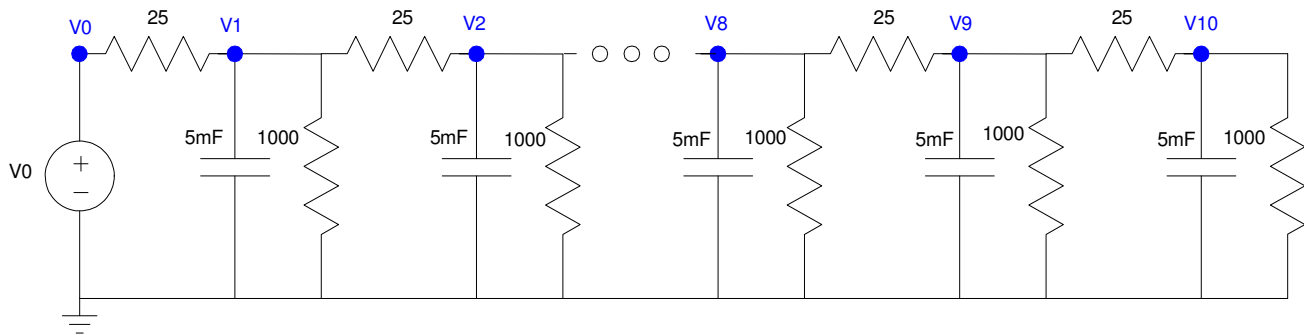
Problem 4-7: 10-Stage RC Filter.

*note: You can turn in the Matlab code along with screen shots of the plots if you like.*

4) For the following 10-stage RC circuit

Specify the dynamics for the system (write N coupled differential equations)

- note: Nodes 1..9 have the same form. Just write the node equation for node 1 and node 10.



$$0.005sV_1 = \left( \frac{V_0 - V_1}{25} \right) + \left( \frac{V_2 - V_1}{25} \right) - \left( \frac{V_1}{1000} \right)$$

$$sV_1 = 8V_0 - 16.2V_1 + 8V_2$$

the same pattern holds for nodes 2..9

$$sV_2 = 8V_1 - 16.2V_2 + 8V_3$$

$$sV_3 = 8V_2 - 16.2V_3 + 8V_4$$

⋮

$$sV_9 = 8V_8 - 16.2V_9 + 8V_{10}$$

Node #10 is the oddball since it only has one 25 ohm resistor connected:

$$0.005sV_{10} = \left( \frac{V_9 - V_{10}}{25} \right) - \left( \frac{V_{10}}{1000} \right)$$

$$sV_{10} = 8V_9 - 8.2V_{10}$$

Express these dynamics in state-space form

$$\begin{bmatrix} sV_1 \\ sV_2 \\ sV_3 \\ sV_4 \\ sV_5 \\ sV_6 \\ sV_7 \\ sV_8 \\ sV_9 \\ sV_{10} \end{bmatrix} = \begin{bmatrix} -16.2 & 8 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 8 & -16.2 & 8 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 8 & -16.2 & 8 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 8 & -16.2 & 8 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 8 & -16.28 & 8 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 8 & -16.2 & 8 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 8 & -16.2 & 8 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 8 & -16.2 & 8 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 8 & -16.2 & 8 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 8 & -8.2 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \\ V_6 \\ V_7 \\ V_8 \\ V_9 \\ V_{10} \end{bmatrix} + \begin{bmatrix} 8 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} V_0$$

Determine the transfer function from V0 to V10

```

>> A = zeros(10,10);
>> for i=1:9
A(i,i) = -16.2;
A(i+1,i) = 8;
A(i,i+1) = 8;
end
>> A(10,10) = -8.2;

```

```

-16.2000    8.0000         0         0         0         0         0         0         0         0
 8.0000  -16.2000    8.0000         0         0         0         0         0         0         0
 0    8.0000  -16.2000    8.0000         0         0         0         0         0         0
 0         0    8.0000  -16.2000    8.0000         0         0         0         0         0
 0         0         0    8.0000  -16.2000    8.0000         0         0         0         0
 0         0         0         0    8.0000  -16.2000    8.0000         0         0         0
 0         0         0         0         0    8.0000  -16.2000    8.0000         0         0
 0         0         0         0         0         0    8.0000  -16.2000    8.0000         0
 0         0         0         0         0         0         0    8.0000  -16.2000    8.0000
 0         0         0         0         0         0         0         0    8.0000  -8.2000

```

```

>> B = [8;0;0;0;0;0;0;0;0;0];
>> C = [0,0,0,0,0,0,0,0,0,1];
>> D = 0;
>> G10 = ss(A,B,C,D);
>> zpk(G10)

```

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---

(s+31.49) (s+29.42) (s+26.18) (s+22.05) (s+17.4) (s+12.64) (s+8.2) (s+4.471) (s+1.784) (s+0.3787)

5) For the transfer function for problem #4

- Determine a 2nd-order approximation for this transfer function
- Plot the step response of the actual 10th-order system and its 2nd-order approximation

Keep the two dominant poles (in blue)

Match the DC gain

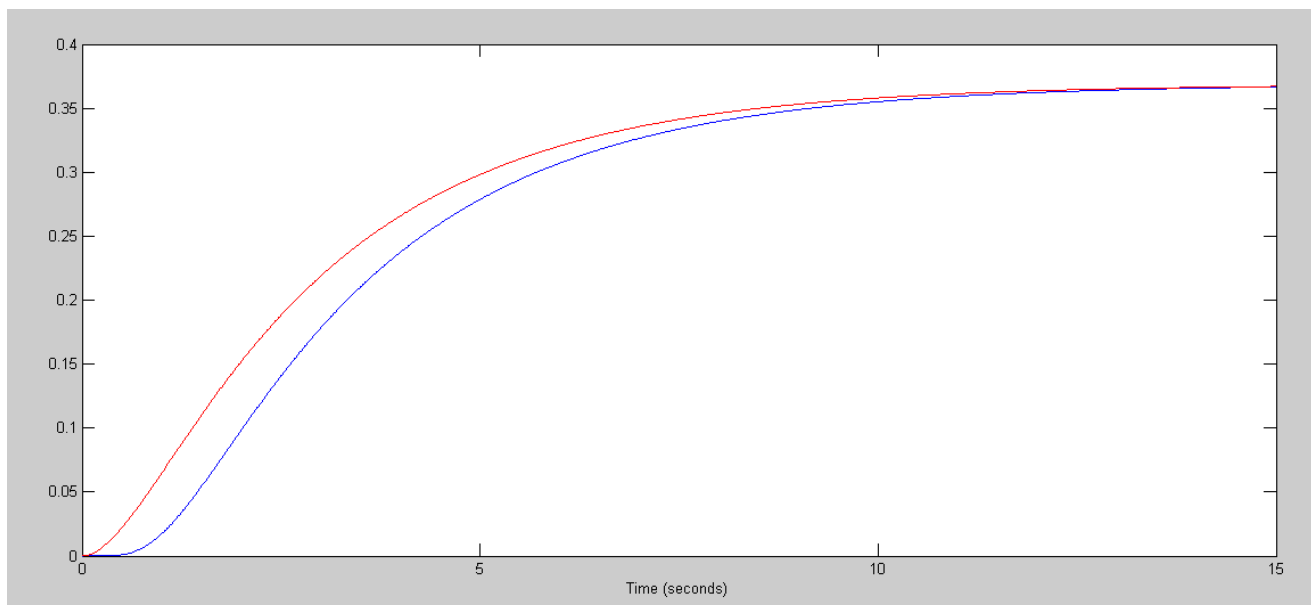
```
>> P = eig(G10)'  
  
-31.4892 -29.4198 -26.1758 -22.0455 -17.3957 -12.6397 -8.2000 -4.4712 -1.7845 -0.3787  
  
>> G2 = zpk([],P(9:10),1);  
>> k = evalfr(G10,0) / evalfr(G2,0)  
  
k = 0.2492  
  
>> G2 = zpk([],P(9:10),k);  
>> zpk(G2)
```

**0.24915**

**(s+1.784) (s+0.3787)**

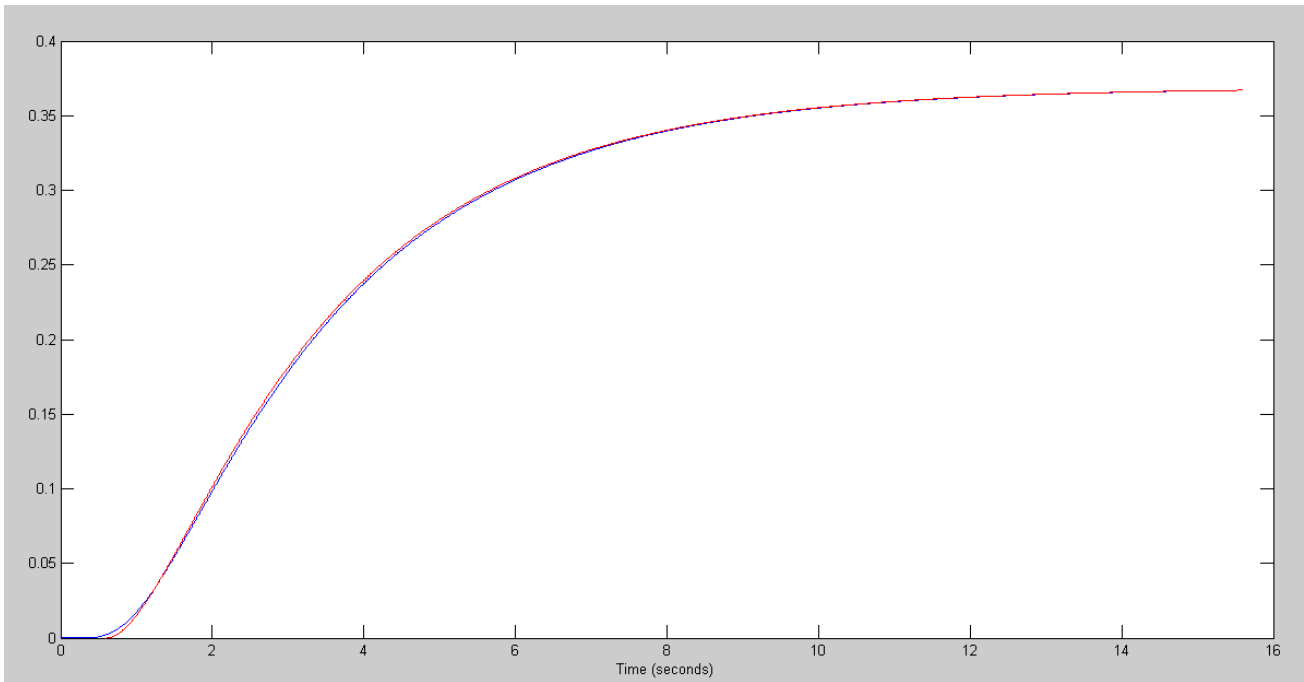
Plot the step responses

```
>> t = [0:0.01:15]';  
>> y10 = step(G10,t);  
>> y2 = step(G2,t);  
>> plot(t,y10,'b',t,y2,'r');  
>> xlabel('Time (seconds)');
```



Note: The fast poles that are ignored look like a 0.6 second delay

```
>> plot(t,y10,'b',t+0.6,y2,'r');  
>> xlabel('Time (seconds)');
```



Step response of 10th-Order System (blue) & 2nd-Order Approximation with a 0.6s delay (red)

This is one way to get a delay in your model (ignored fast poles)



## 6) For the circuit for problem #4

- What initial condition will decay as slowly as possible?
- What initial condition will decay as fast as possible?

This is an eigenvector problem

```
>> [M,V] = eig(A);
>> M

M =

-0.1286  -0.2459  0.3412  0.4063  0.4352  0.4255  0.3780  0.2969  -0.1894  0.0650
 0.2459   0.4063  -0.4255  -0.2969  -0.0650  0.1894  0.3780  0.4352  -0.3412  0.1286
-0.3412  -0.4255  0.1894  -0.1894  -0.4255  -0.3412  -0.0000  0.3412  -0.4255  0.1894
 0.4063   0.2969  0.1894  0.4352  0.1286  -0.3412  -0.3780  0.0650  -0.4255  0.2459
-0.4352  -0.0650  -0.4255  -0.1286  0.4063  0.1894  -0.3780  -0.2459  -0.3412  0.2969
 0.4255  -0.1894  0.3412  -0.3412  -0.1894  0.4255  0.0000  -0.4255  -0.1894  0.3412
-0.3780   0.3780  -0.0000  0.3780  -0.3780  -0.0000  0.3780  -0.3780  -0.0000  0.3780
 0.2969  -0.4352  -0.3412  0.0650  0.2459  -0.4255  0.3780  -0.1286  0.1894  0.4063
-0.1894  0.3412  0.4255  -0.4255  0.3412  -0.1894  -0.0000  0.1894  0.3412  0.4255
 0.0650  -0.1286  -0.1894  0.2459  -0.2969  0.3412  -0.3780  0.4063  0.4255  0.4352

>> eig(A) '

ans =

-31.4892  -29.4198  -26.1758  -22.0455  -17.3957  -12.6397  -8.2000  -4.4712  -1.7845  -0.3787
```

The fast mode (red) decays quickly

```
>> X0 = M(:,1) * 20

-2.5728
 4.9171
-6.8244
 8.1253
-8.7043
 8.5099
-7.5593
 5.9370
-3.7872
 1.3009
```

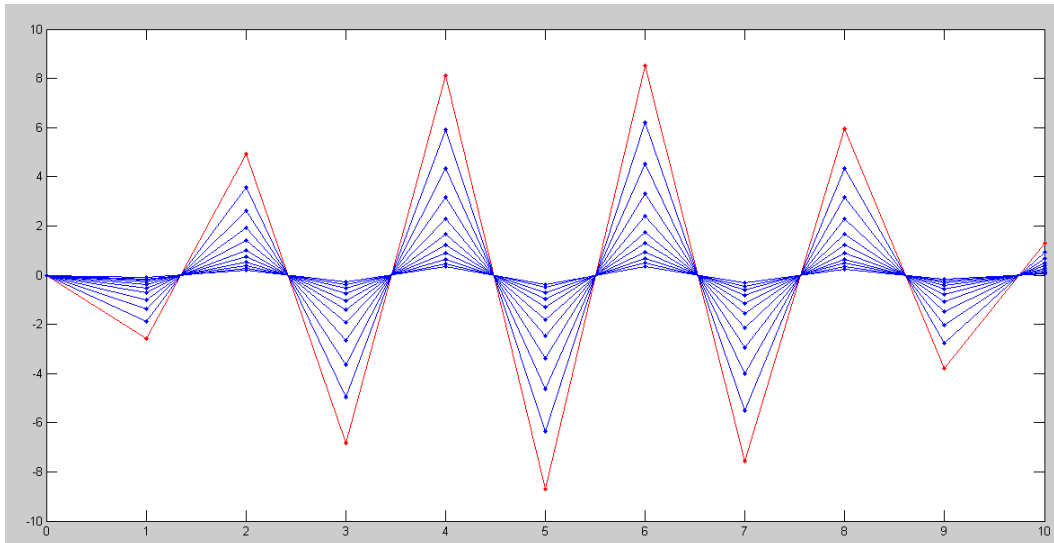
The slow mode (blue) decays slowly

```
>> X0 = M(:,10) * 20

1.3009
2.5728
3.7872
4.9171
5.9370
6.8244
7.5593
8.1253
8.5099
8.7043
```

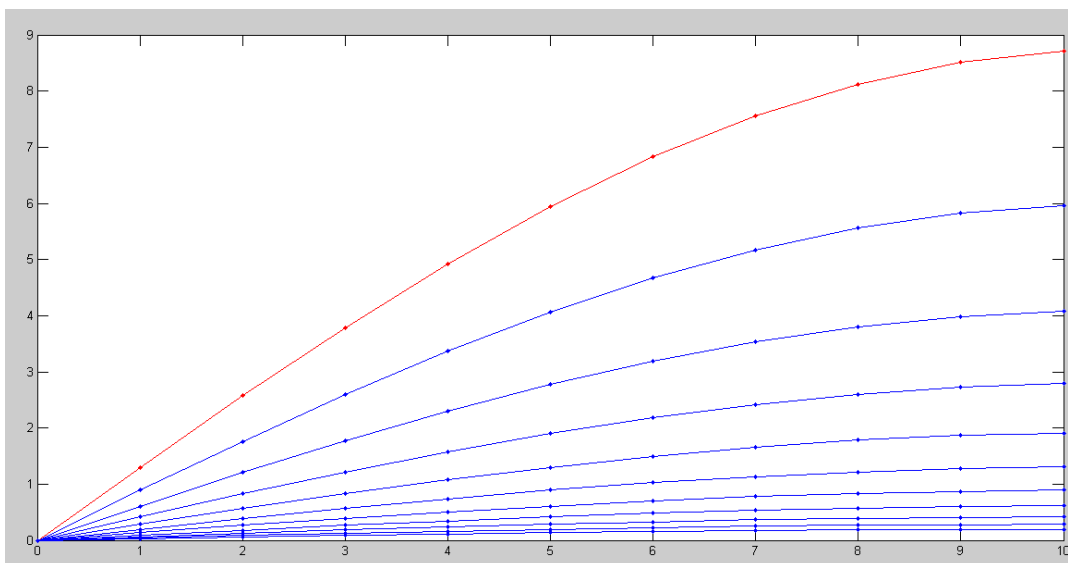
7) Modify the program *heat.m* to match the dynamics you calculated for this problem.

- Give the program listing
- Give the response for  $V_{in} = 0$  and the initial conditions being
  - The slowest eigenvector
  - The fastest eigenvector
  - A random set of voltages



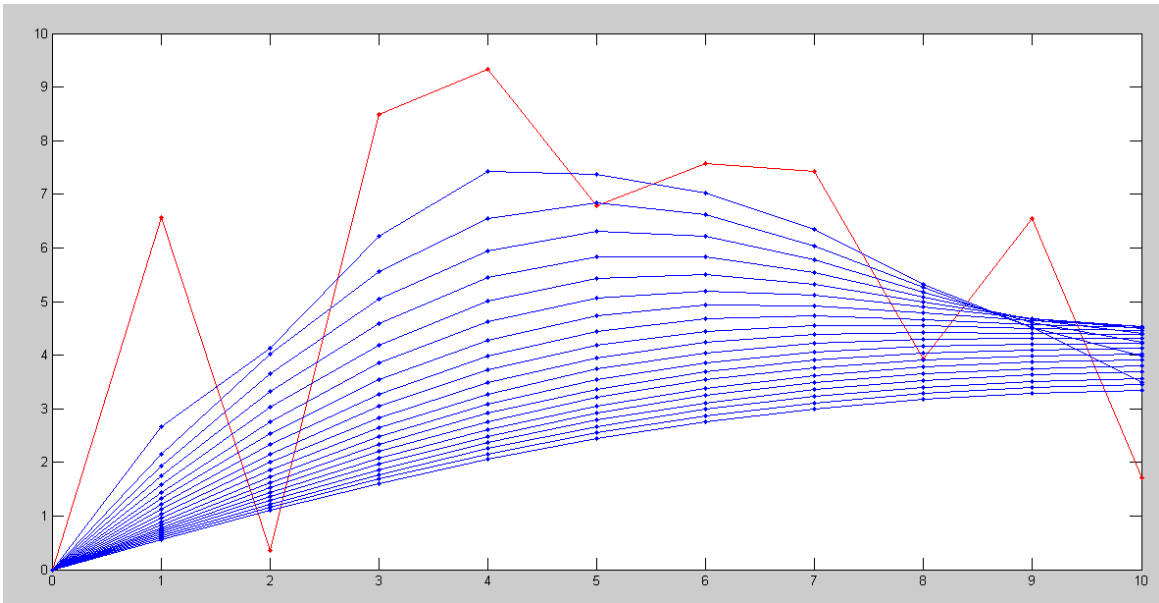
Fast mode: Voltages plotted every 10ms

Note: The shape stays the same (the eigenvector). The amplitude decays quickly (the eigenvalue)



Slow Mode: Voltages Plotted every 1.00 second

Note: The shape stays the same (the eigenvector). The amplitude decays slowly (the eigenvalue)



Random Initial Conditions.  
Fast modes decay quickly, leaving the slow (dominant) mode

## Code:

```
% 10-stage RC Filter

% V = M(:,10) * 20;
% V = M(:,1) * 20;
V = 10*rand(10,1)

dV = zeros(10,1);
V0 = 0;
dt = 0.001;
t = 0;
i = 0;

y = [];

hold off
plot([0,10],[0,100],'w. ');
plot([0:10],[V0;V], 'r.-');
pause(0.01);

hold on

while(t < 2)
    dV(1) = 8*V0 - 16.2*V(1) + 8*V(2);
    dV(2) = 8*V(1) - 16.2*V(2) + 8*V(3);
    dV(3) = 8*V(2) - 16.2*V(3) + 8*V(4);
    dV(4) = 8*V(3) - 16.2*V(4) + 8*V(5);
    dV(5) = 8*V(4) - 16.2*V(5) + 8*V(6);
    dV(6) = 8*V(5) - 16.2*V(6) + 8*V(7);
    dV(7) = 8*V(6) - 16.2*V(7) + 8*V(8);
    dV(8) = 8*V(7) - 16.2*V(8) + 8*V(9);
    dV(9) = 8*V(8) - 16.2*V(9) + 8*V(10);
    dV(10) = 8*V(9) - 8.2*V(10);

    V = V + dV*dt;
    t = t + dt;

    y = [y ; V'];
    i = mod(i + 1, 100);
    if(i == 0)
        plot([0:10],[V0;V], 'r.-');
        pause(0.01);
    end
end

end
```