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# **Pascal Distribution**

## **ECE 341: Random Processes**

### **Lecture #11**

note: All lecture notes, homework sets, and solutions are posted on [www.BisonAcademy.com](http://www.BisonAcademy.com)

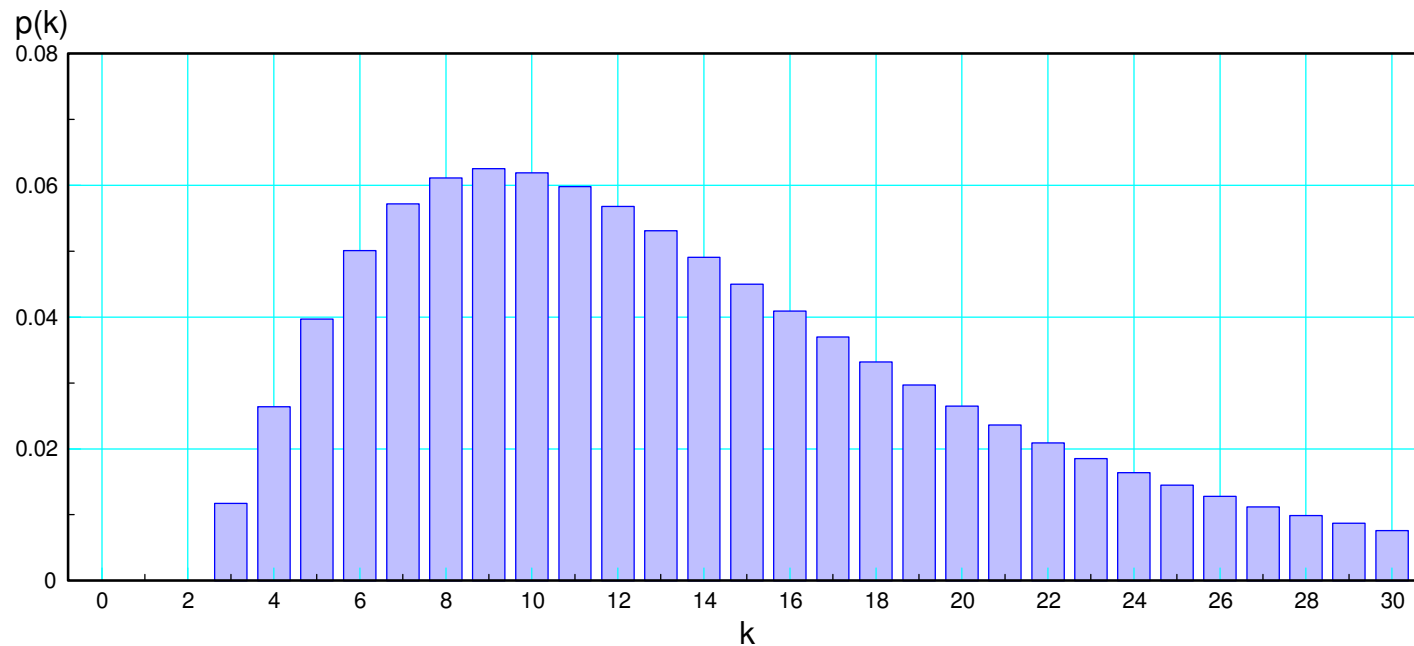
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# Pascal Distribution (a.k.a. Negative Binomial Distribution)

A Pascal distribution is similar to a geometric distribution, modeling

- The number of times you roll a die until you get  $r$  ones
- The number of times you make a trip with a car until  $r$  things fail (and it's time to buy a new car)
- The number of days until  $r$  accidents happen at work and you're promoted (Peter principle)



## pdf - mgf - mean - variance

| Distribution             | description                            | pdf                                                  | mgf                                                  | mean                           | variance                                |
|--------------------------|----------------------------------------|------------------------------------------------------|------------------------------------------------------|--------------------------------|-----------------------------------------|
| Bernoulli trial          | flip a coin<br>obtain m heads          | $p^m q^{1-m}$                                        | $q + p/z$                                            | p                              | p(1-p)                                  |
| Binomial                 | flip n coins<br>obtain m heads         | $\binom{n}{m} p^m q^{n-m}$                           | $(q + p/z)^n$                                        | np                             | np(1-p)                                 |
| Hyper Geometric          | Bernoulli trial without<br>replacement | $\frac{\binom{A}{x} \binom{B}{n-x}}{\binom{A+B}{n}}$ |                                                      |                                |                                         |
| Uniform<br>range = (a,b) | toss an n-sided die                    | $1/n \quad a \leq m \leq b$<br>$0 \quad otherwise$   | $\left( \frac{1+z+z^2+\dots+z^{n-1}}{n z^b} \right)$ | $\left( \frac{a+b}{2} \right)$ | $\left( \frac{(b+1-a)^2-1}{12} \right)$ |
| Geometric                | Bernoulli until 1st<br>success         | $p q^{k-1}$                                          | $\left( \frac{p}{z-q} \right)$                       | $\left( \frac{1}{p} \right)$   | $\left( \frac{q}{p^2} \right)$          |
| Pascal                   | Bernoulli until rth<br>success         | $\binom{x-1}{r-1} p^r q^{x-r}$                       | $\left( \frac{p}{z-q} \right)^r$                     | $\left( \frac{r}{p} \right)$   | $\left( \frac{qr}{p^2} \right)$         |

Source: Wikipedia

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## pdf for a Pascal Distribution

Assume you toss a coin with the probability of heads being  $p$ .

The probability of getting  $r$  heads on  $k$ th flip is:

- On the  $k$ th flip, you must get a heads (probability =  $p$ ):
- On the previous  $k-1$  flips, you got  $r-1$  heads. ( binomial distribution )

$$f(k) = \binom{k-1}{r-1} p^{r-1} q^{(k-1)-(r-1)}$$

- Both must happen

$$f(k) = p \cdot \binom{k-1}{r-1} p^{r-1} q^{(k-1)-(r-1)} = \binom{k-1}{r-1} p^r q^{k-r}$$

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## Mean and Variance

The moment generating function for a geometric distribution is

$$\psi(z) = \left( \frac{p}{z-q} \right)$$

The moment generating for  $r$  geometric distributions (a Pascal distribution) is

$$\psi(z) = \left( \frac{p}{z-q} \right)^r$$

### Zeroth Moment

$$m_0 = \psi(z-1) = 1$$

$$m_0 = \left( \frac{p}{1-q} \right)^r = 1^r = 1$$

This is a valid moment generating function (probabilities add to one)

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## 1st Moment (mean)

$$m_1 = -\psi'(z = 1)$$

$$m_1 = -\frac{d}{dz} \left( \left( \frac{p}{z-q} \right)^r \right)_{z=1}$$

$$m_1 = - \left( \frac{-r \cdot p^r}{(z-q)^{r+1}} \right)_{z=1}$$

$$m_1 = \left( \left( \frac{r \cdot p^r}{(p)^{r+1}} \right) \right) = \left( \frac{r}{p} \right)$$

$$\mu = m_1 = \left( \frac{r}{p} \right)$$

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## Second Moment

$$m_2 = \psi''(z=1)$$

$$m_1 = \frac{d^2}{dz^2} \left( \left( \frac{p}{z-q} \right)^r \right)_{z=1}$$

$$m_2 = \left( \frac{d}{dz} \left( \frac{-r \cdot p^r}{(z-q)^{r+1}} \right) \right)_{z=1}$$

$$m_2 = \left( \left( \frac{r(r+1)p^r}{(z-q)^{r+2}} \right) \right)_{z=1}$$

$$m_2 = \left( \left( \frac{r(r+1)p^r}{p^{r+2}} \right) \right)$$

$$m_2 = \left( \frac{r(r+1)}{p^2} \right)$$

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Variance:

$$\sigma^2 = m_2 - m_1 - m_1^2$$

$$\sigma^2 = \left( \frac{r(r+1)}{p^2} \right) - \left( \frac{r}{p} \right) - \left( \frac{r}{p} \right)^2$$

$$\sigma^2 = \left( \frac{r^2 + r - pr - r^2}{p^2} \right)$$

$$\sigma^2 = \left( \frac{r(1-p)}{p^2} \right)$$

$$\sigma^2 = \left( \frac{qr}{p^2} \right)$$

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## Example 1: Roll Until 1 Success

- Rolling a die until you get a 1 or 2
- The number of times you do the dishes until someone notices
- The number of parties you go to until you catch COVID-19

Solution: This is a geometric distribution

$$p(k) = \left(\frac{1}{3}\right) \left(\frac{2}{3}\right)^{k-1} u(k-1)$$

Matlab Code:

```
k = [1:30]';  
A = (1/3) * (2/3) .^ (k-1) .* (k-1 >= 0);  
k = [0;k];  
A = [0;A];  
  
bar(k,A)
```

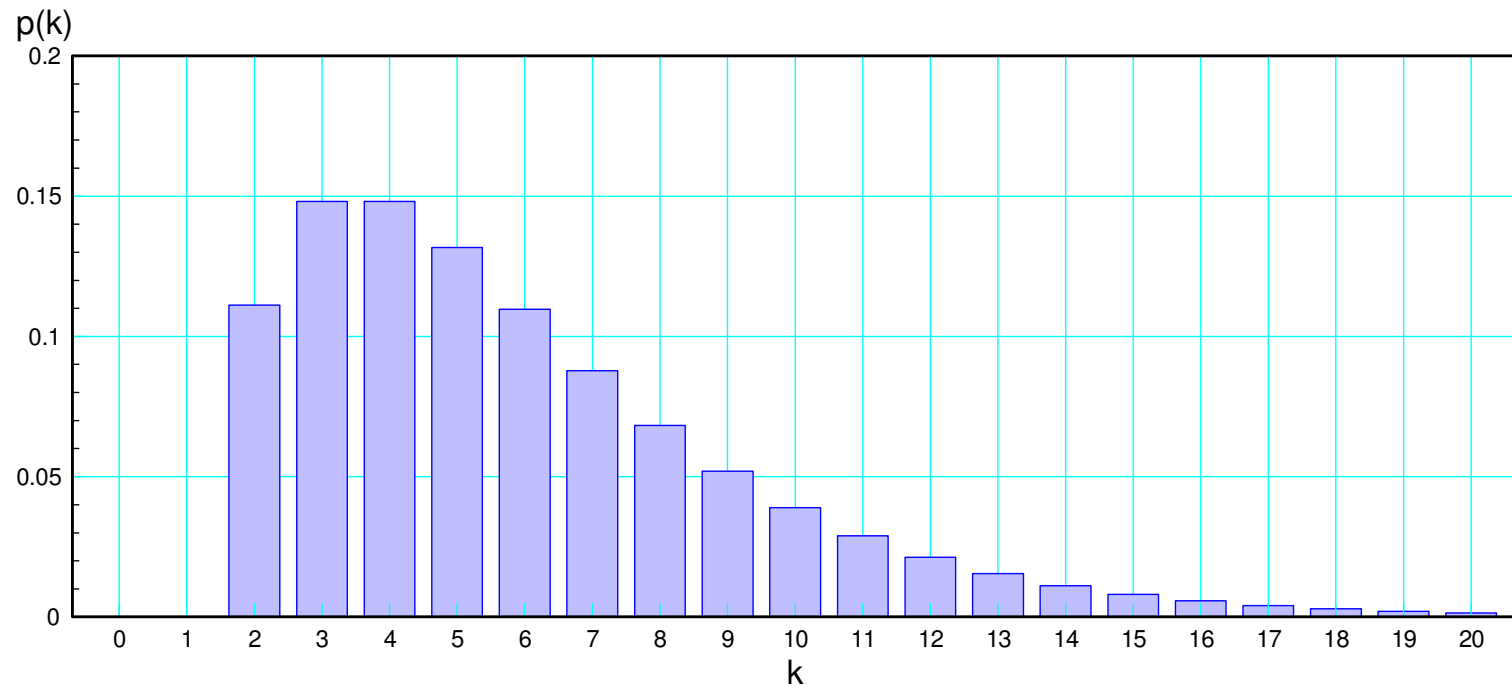


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## Example 2: Roll until you get 2 successes

- The number of times you roll a 6-sided die until you roll a 1 or 2 twice (  $p = 1/3$  )
- The number of times you do the dishes until two people notice (  $p = 1/3$  )
- The number of parties you go to until you have two exposes to COVID-19 (assume  $p = 1/3$  )

Solution: This is a Pascal distribution.



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## Option 1: Convolution in matlab.

- We have the pdf for  $r = 1$  from before
- Use convolution to repeat the event

```
A2 = conv(A,A);  
[k(1:21), A2(1:21)]
```

| k       | A2     |
|---------|--------|
| 0       | 0      |
| 1.0000  | 0      |
| 2.0000  | 0.1111 |
| 3.0000  | 0.1481 |
| 4.0000  | 0.1481 |
| 5.0000  | 0.1317 |
| 6.0000  | 0.1097 |
| 7.0000  | 0.0878 |
| 8.0000  | 0.0683 |
| 9.0000  | 0.0520 |
| 10.0000 | 0.0390 |
| 11.0000 | 0.0289 |

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## Option 2: Use the Pascal distribution formula

$$p(k) = \binom{k-1}{r-1} p^r q^{k-r}$$

```
p = 1/3;  
q = 2/3;  
r = 2;  
B = zeros(21,1);  
for i=3:20  
    k = i-1;  
    B(i) = NchooseM(k-1, r-1) * p^r * q^(k-r) .* (k >= 0);  
end  
  
k = [0:20]';  
[k(1:21), A2(1:21), B(1:21)]
```

| k      | conv   | formula |
|--------|--------|---------|
| 0      | 0      | 0       |
| 1.0000 | 0      | 0       |
| 2.0000 | 0.1111 | 0.1111  |
| 3.0000 | 0.1481 | 0.1481  |
| 4.0000 | 0.1481 | 0.1481  |
| 5.0000 | 0.1317 | 0.1317  |
| 6.0000 | 0.1097 | 0.1097  |

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### Option 3: z-transforms

The moment-generating function (i.e. z-transform) for a geometric distribution is

$$\psi(z) = \left( \frac{p}{z-q} \right)$$

Doing this twice gives

$$\psi(z) = \left( \frac{p}{z-q} \right)^2 = \left( \frac{1/3}{z-2/3} \right)^2$$

Take the inverse z-transform. From a table of z-transforms:

$$\left( \frac{z}{(z-a)^2} \right) \leftrightarrow \left( \frac{k}{1!} \right) a^{k-1}$$

so

$$\left( \frac{1/3}{z-2/3} \right)^2 = \left( \frac{1}{9z} \right) \left( \frac{z}{(z-2/3)^2} \right) \rightarrow \left( \frac{1}{9z} \right) k \left( \frac{2}{3} \right)^{k-1} u(k)$$

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1/z means delay by one

$$p(k) = \left(\frac{1}{9}\right) (k-1) \left(\frac{2}{3}\right)^{k-2} u(k-1)$$

## Checking in Matlab

```
C = zeros(21,1);  
for i=3:21  
    k = i-1;  
    C(i) = (1/9)*(k-1)* ( (2/3)^(k-2) );  
end
```

```
k = [0:20]';  
[k(1:21), A2(1:21), B(1:21), C(1:21)]
```

| k | conv   | formula | z-trans |
|---|--------|---------|---------|
| 0 | 0      | 0       | 0       |
| 1 | 0      | 0       | 0       |
| 2 | 0.1111 | 0.1111  | 0.1111  |
| 3 | 0.1481 | 0.1481  | 0.1481  |
| 4 | 0.1481 | 0.1481  | 0.1481  |
| 5 | 0.1317 | 0.1317  | 0.1317  |
| 6 | 0.1097 | 0.1097  | 0.1097  |
| 7 | 0.0878 | 0.0878  | 0.0878  |

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## Example 3: Combining Geometric Distributions

Assume you are rolling an 8-sided die

Let

- A be the number of rolls until you roll a 1 (  $p = 1/8$  )
- B be the number of rolls until you roll a 1 or 2 (  $p = 2/8$  )
- C be the number of rolls until you roll a 1, 2, or 3 (  $p = 3/8$  )

Determine the pdf for  $A + B + C$



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## Solution using Matlab and Convolutions:

A, B, and C are geometric distributions

$$A(k) = \left(\frac{1}{8}\right) \left(\frac{7}{8}\right)^{k-1} u(k-1)$$

$$B(k) = \left(\frac{2}{8}\right) \left(\frac{6}{8}\right)^{k-1} u(k-1)$$

$$C(k) = \left(\frac{3}{8}\right) \left(\frac{5}{8}\right)^{k-1} u(k-1)$$

Use Matlab to convolve the three together

```
A = (1/8) * (7/8) .^ (k-1) .* (k-1 >= 0);  
B = (2/8) * (6/8) .^ (k-1) .* (k-1 >= 0);  
C = (3/8) * (5/8) .^ (k-1) .* (k-1 >= 0);
```

| k      | A      | B      | C      |
|--------|--------|--------|--------|
| 0      | 0      | 0      | 0      |
| 1.0000 | 0.1250 | 0.2500 | 0.3750 |
| 2.0000 | 0.1094 | 0.1875 | 0.2344 |
| 3.0000 | 0.0957 | 0.1406 | 0.1465 |
| 4.0000 | 0.0837 | 0.1055 | 0.0916 |



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## Now convolve them

```
AB = conv(A,B);  
ABC = conv(AB,C);  
[k(1:21),ABC(1:21)]
```

| k  | p(k)   |
|----|--------|
| 0  | 0      |
| 1  | 0      |
| 2  | 0      |
| 3  | 0.0117 |
| 4  | 0.0264 |
| 5  | 0.0397 |
| 6  | 0.0501 |
| 7  | 0.0572 |
| 8  | 0.0611 |
| 9  | 0.0625 |
| 10 | 0.0619 |

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## Option 2: z-transforms

$$A(z) = \left( \frac{1/8}{z-7/8} \right)$$

$$B(z) = \left( \frac{2/8}{z-6/8} \right)$$

$$C(z) = \left( \frac{3/8}{z-5/8} \right)$$

The z-transform for the sum of the three is

$$Y(z) = A(z) \cdot B(z) \cdot C(z)$$

$$Y(z) = \left( \frac{1/8}{z-7/8} \right) \left( \frac{2/8}{z-6/8} \right) \left( \frac{3/8}{z-5/8} \right)$$

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This isn't in the table of z-transforms, so use partial fraction expansion

$$Y(z) = \left( \frac{1/8}{z-7/8} \right) \left( \frac{2/8}{z-6/8} \right) \left( \frac{3/8}{z-5/8} \right)$$

$$Y(z) = \left( \frac{0.375}{z-7/8} \right) + \left( \frac{-0.75}{z-6/8} \right) + \left( \frac{0.375}{z-5/8} \right)$$

Multiply both sides by z

$$zY = \left( \frac{0.375z}{z-7/8} \right) + \left( \frac{-0.75z}{z-6/8} \right) + \left( \frac{0.375z}{z-5/8} \right)$$

$$z \cdot y(k) = \left( 0.375 \left( \frac{7}{8} \right)^k - 0.75 \left( \frac{6}{8} \right)^k + 0.375 \left( \frac{5}{8} \right)^k \right) u(k)$$

Divide by z (delay by 1)

$$y(k) = \left( 0.375 \left( \frac{7}{8} \right)^{k-1} - 0.75 \left( \frac{6}{8} \right)^{k-1} + 0.375 \left( \frac{5}{8} \right)^{k-1} \right) u(k-1)$$

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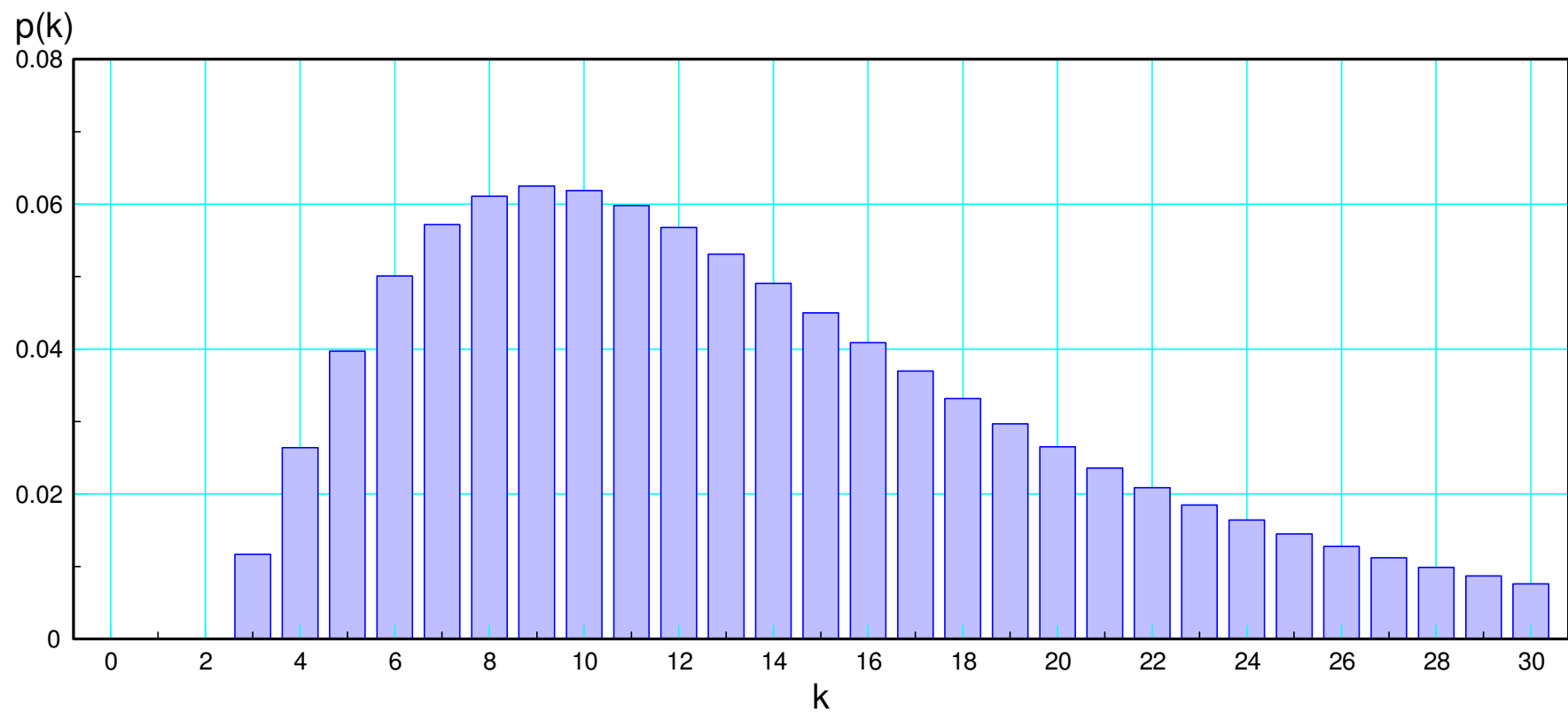
## Checking against the results for convolution:

```
k = [0:31]';  
Y = 0*k;  
Y = ( 0.375*(7/8).^ (k-1) - 0.75*(6/8).^ (k-1) + 0.375*(5/8).^ (k-1) ) .*  
(k-1>0);  
  
[k(1:21),ABC(1:21),Y(1:21)]
```

| k  | conv   | z-trans |
|----|--------|---------|
| 0  | 0      | 0       |
| 1  | 0      | 0       |
| 2  | 0      | 0       |
| 3  | 0.0117 | 0.0117  |
| 4  | 0.0264 | 0.0264  |
| 5  | 0.0397 | 0.0397  |
| 6  | 0.0501 | 0.0501  |
| 7  | 0.0572 | 0.0572  |
| 8  | 0.0611 | 0.0611  |
| 9  | 0.0625 | 0.0625  |
| 10 | 0.0619 | 0.0619  |
| 11 | 0.0598 | 0.0598  |

Either method is valid: they give you the same results.

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pdf for the number of rolls of an 8-sided die until you roll a 1, then a 1 or 2, then a 1, 2, or 3

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## Example 3:

Determine the pdf for  $X$  where  $X$  is the total number of die rolls:

- Roll an 8-sided die until you get four ones, then
- Roll a 6-sided die until you get two ones.



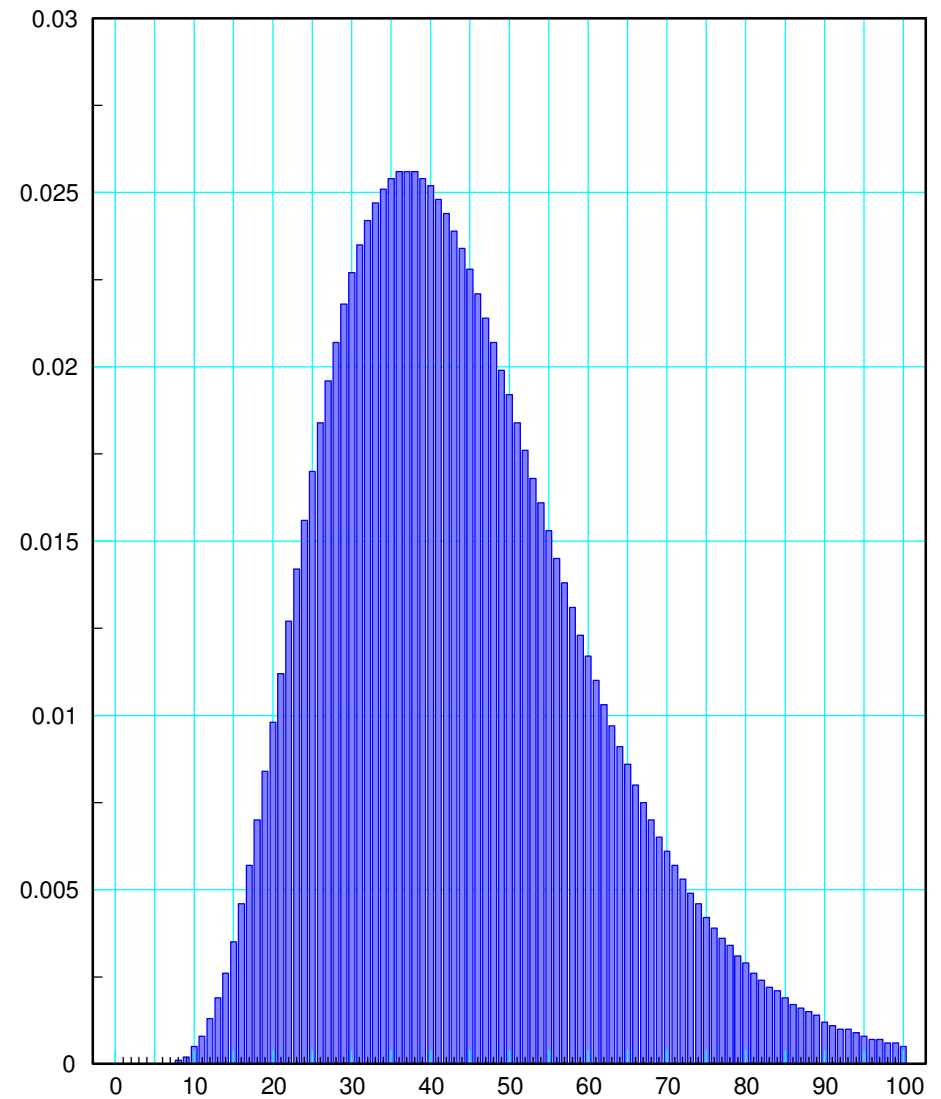
### Matlab Code

```
>> k = [0:100]';  
>> d8 = 1/8 * (7/8) .^ (k-1);  
>> d8(1) = 0;  
>> d6 = 1/6 * (5/6) .^ (k-1);  
>> d6(1) = 0;  
>> d8x2 = conv(d8,d8);  
>> d8x4 = conv(d8x2,d8x2);  
>> d6x2 = conv(d6,d6);  
>> X = conv(d8x4,d6x2);  
>> sum(X)
```

```
ans =      1.0000
```

```
>> X = X(1:101);  
>> bar(k,X)
```

### pdf



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## Find an equation for the pdf:

- z-transforms helps here

The number of die rolls until you get a one on a 6 and 8-sided die:

$$d6 = \left( \frac{1/6}{z-5/6} \right) \quad d8 = \left( \frac{1/8}{z-7/8} \right)$$

The number of die rolls until you four 1's on a d8 and two 1's on d6

$$X = \left( \frac{1/6}{z-5/6} \right)^2 \left( \frac{1/8}{z-7/8} \right)^4$$

Now take the inverse z-transform

- partial fractions is going to be a pain...
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## Engineering Solution

- Change the problem so that it's easier to solve
- While keeping the flavor of the actual problem

### Change X

$$X = \left( \frac{1/6}{z-0.8333} \right)^2 \left( \frac{1/8}{z-0.8750} \right)^4$$

to

$$X \approx \left( \frac{-}{z-0.8323} \right) \left( \frac{-}{z-0.8343} \right) \left( \frac{-}{z-0.873} \right) \left( \frac{-}{z-0.874} \right) \left( \frac{-}{z-0.876} \right) \left( \frac{-}{z-0.877} \right)$$

### Adjust the numerator so the DC gain is 1.000

- the zeroth moment is 1.000
  - this is a valid PDF
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$$X = \left( \frac{0.1677}{z-0.8323} \right) \left( \frac{0.1657}{z-0.8343} \right) \left( \frac{0.127}{z-0.873} \right) \left( \frac{0.126}{z-0.874} \right) \left( \frac{0.124}{z-0.876} \right) \left( \frac{0.123}{z-0.877} \right)$$

This has a delay of six, so multiply by  $z^6$

$$z^6 X = \left( \frac{0.1677z}{z-0.8323} \right) \left( \frac{0.1657z}{z-0.8343} \right) \left( \frac{0.127z}{z-0.873} \right) \left( \frac{0.126z}{z-0.874} \right) \left( \frac{0.124z}{z-0.876} \right) \left( \frac{0.123z}{z-0.877} \right)$$

Now do partial fractions (keep lots of decimal places)

$$z^6 X = \left( \frac{az}{z-0.8323} \right) + \left( \frac{bz}{z-0.8343} \right) + \left( \frac{cz}{z-0.873} \right) + \left( \frac{dz}{z-0.874} \right) + \left( \frac{ez}{z-0.876} \right) + \left( \frac{fz}{z-0.877} \right)$$

Take the inverse z-transform

$$x(k+6) = a(0.8323)^k + b(0.8343)^k + c(0.873)^k + d(0.874)^k + e(0.876)^k + f(0.877)^k$$


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## The results is almost the same

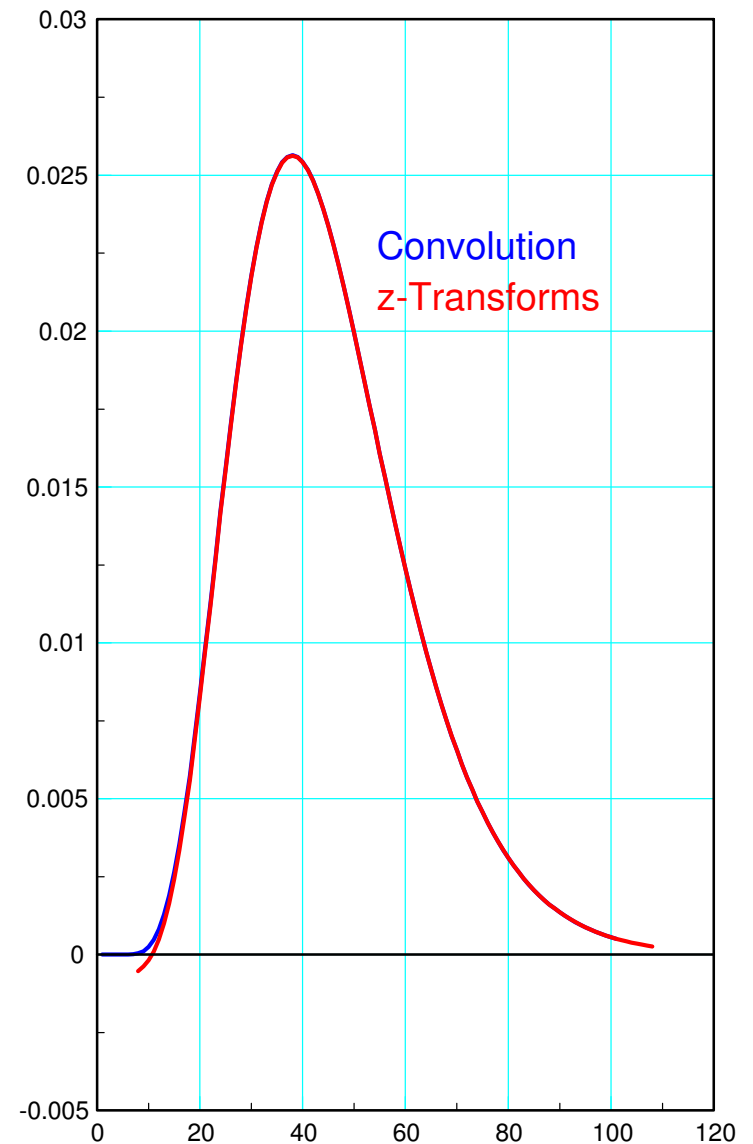
```
poles = [0.8323,0.8343,0.873,0.874,0.876,0.877];
G = zpk([0,0,0,0,0],poles,1,1);
DC = evalfr(G,1);
k = 1/DC;
G = zpk([0,0,0,0,0],poles,k,1);

eps = 1e-12'

z = 0.8323 + eps;
a = evalfr(G,z) * (z-0.8323);
z = 0.8343 + eps;
b = evalfr(G,z) * (z-0.8343);
z = 0.873 + eps;
c = evalfr(G,z) * (z-0.873);
z = 0.874 + eps;
d = evalfr(G,z) * (z-0.874);
z = 0.876 + eps;
e = evalfr(G,z) * (z-0.876);
z = 0.877 + eps;
f = evalfr(G,z) * (z-0.877);

k = [1:101]';
Y = a*0.8323.^k + b*0.8343.^k + c*0.873.^k +
d*0.874.^k + e*0.876.^k + f*0.877.^k;

plot(k,X,k+7,Y)
```



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# Summary

A Pascal distribution is an extension of a geometric distribution

- The number of rolls until  $k$  events happen

This is where z-transforms shine

- They make computing the mean and variance easier
- They make combining geometric distributions easier