

# Homework #10: ECE 461/661

z-Transforms, s to z conversion, Root Locus in the z-Domain. Due Monday, November 10th

## z-Transforms

- 1) Determine the difference equation that relates  $X$  and  $Y$

$$Y = \left( \frac{0.005z}{(z-0.98)(z-0.95)(z-0.8)} \right) X$$

- 2) Determine  $y(k)$  assuming

$$Y = \left( \frac{0.005z}{(z-0.98)(z-0.95)(z-0.8)} \right) X \quad x(t) = 2 \cos(3t) + 4 \sin(3t)$$
$$T = 0.1$$

- 3) Determine  $y(k)$  assuming

$$Y = \left( \frac{0.005z}{(z-0.98)(z-0.95)(z-0.8)} \right) X \quad x(k) = u(k)$$

## s to z conversion

- 4) Determine the discrete-time equivalent of  $G(s)$ . Assume  $T = 0.5$  second
- 5) Determine the discrete-time equivalent of  $G(s)$ . Assume  $T = 0.1$  second

$$G(s) = \left( \frac{170}{(s+0.47)(s+3.40)(s+9.00)(s+16.77)} \right)$$

## Root Locus in the z-Domain

Assume  $T = 0.1$  seconds.

$$G(s) = \left( \frac{170}{(s+0.47)(s+3.40)(s+9.00)(s+16.77)} \right)$$

- 6) Draw the root locus for  $G(z)$
- 7) Find  $k$  for no overshoot in the step response
- Simulate the closed-loop system's step response
- 8) Find  $k$  for 20% overshoot for a step response (damping ratio = 0.4559)
- Simulate the closed-loop system's step response
- 9) Find  $k$  for a damping ratio of 0.00
- Simulate the closed-loop system's step response

