Introduction & Syllabus

ECE 476 Embedded Systems Jake Glower - Lecture #1

Please visit Bison Academy for corresponding lecture notes, homework sets, and solutions

What Are Embedded Systems?

Electronics which includes a microcontroller

- Inputs: Sensors, what's happening?
- Outputs: Actuators: do something
- Microcontroller: Use software to control the outputs based upon the inputs

This is a fun course where you build, program, test, and demonstrate various devices

• Having a microcontroller allows you to much more than you could in other classes, much easier



Senior-Level Course

- Students don't know what they don't know
- 35 lectures = 35 things you can do with a microcontroller

What is Advanced Embedded Systems?

Three programming levels:

- Low-Level (ECE 376)
 - Focus on driver routines to access the hardware
 - Directly control registers, I/O pins
 - Assembler & C programming languages
 - example: how to generate a 100Hz, 30% duty cycle square wave
- Mid-Level (ECE 476)
 - Focus on more complicated programs
 - Use driver routines to access the hardware
 - Python programming language
 - example: Control the speed of a motor using PWM
- High-Level (CSCI 4xx)
 - Focus on more complicated programs
 - Use lower-level routines to do task
 - AI languages
 - example: Get quad-copters to swarm

High-Level

Raspberry Pi Al / Swarm / Search

NDSU CSCI 4xx

Mid-Level

Python
Raspberry-Pi Pico
Get quad-copter to hover

NDSU ECE 476

Low-Level

C & Assembler PIC18F4620 Create PWM signals

NDSU ECE 376

ECE 376 vs. ECE 476

ECE 376: Embedded Systems	ECE 476: Advanced Embedded
Low-Level Programming	Mid-Level Programming
 Focus on driver routines 	Call driver routines
 Access hardware 	 Focus on more complex tasks
 Setting control registers 	Python
Assembler & C	• Slower
• Fast	 Easier to write and debug code
 Access to hardware 	Microcontroller
Microcontroller	• Raspberry Pi-Pico (RP2040)
• PIC18F4620	I/O
I/O	• Serial port (SCI)
 Binary (LEDs) 	 Graphics LCD display
 LCD character display 	 Analog inputs (A/D)
 Analog inputs 	Analog outputs (PWM)

Do I Need ECE 376 Embedded Systems?

Not really

- Different processor
- Different language
- Different objectives

If you need a refresher

- Bison Academy
 - https://www.BisonAcademy.com/Index
- ECE 320 Electronics
 - https://www.BisonAcademy.com/ECE320/Index
- ECE 376 Embedded Systems
 - https://www.BisonAcademy.com/ECE376/Index

What's New: Processor

Raspberry Pi Pico W

- \$9 from Amazon
- \$6 from Adafruit or the Pi-Shop

Features

- Dual ARM Cortex-M0+ @ 133MHz
- 2MB Flash
- 264kB on-chip SRAM in six independent banks
- 30 GPIO pins
 - 3.3V fixed
 - 12mA source/sink
- 4 x 12-bit, 500ksps A/D (3 external connections)
- $2 \times UART$, $2 \times I2C$, $2 \times SPI$, $16 \times PWM$ channels
- $1 \times \text{Timer with 4 alarms}$, $1 \times \text{Real Time Counter}$
- 8 state machines total
- Bluetooth
- Wi-Fi



What's New: Development Board

- GeeekPi Pico Breadboard Kit Plus Version
- \$32 from Amazon

Features:

- I/O pins connected to headers
- 2 x Push Buttons
- 2 x LEDs
- 1 x Beeper
- XY joystick (analog inputs)
- RGB LED (NeoPixel)
- 320 x 480 graphics LCD
 - with touch-screen
- Total Current Draw:
 - 272mA when LCD is black
 - Pico-W = 20.7mA



What's New: Python

- Thonny programmer (free!)
- Windows compatible

Very similar to Matlab

- Similar syntax
- Works with complex numbers
- Easily read/write to console
- Interpritive language
 - Can test your code in the command window

```
Thonny - <untitled> @ 1:17
File Edit View Run Tools Help
Speed_Control.py × <untitled> * ×
  1 # Program Window
Shell
 MPY: soft reboot
MicroPython v1.22.2 on 2024-02-22; Raspberr
ith RP2040
Type "help()" for more information.
>>> print('Hello World')
  Hello World
>>> X = 2**0.5
>>> print('X = ',X)
 X = 1.414214
>>>
```

Course Content

- Lectures 1-11
- Python Programming

How to read and write in Python

- Binary signals
- Analog signals
- Use of libraries

How to measure time

• and output frequencies

How to drive different motors

- motors with binary inputs
- motors with analog inputs

1	Introduction & Syllabus
2	Thonny & MicroPython
3	Loops & If-Statements
4	Subroutines
5	Binary Outputs
6	Binary Inputs
7	Serial I/O
8	Timing
9	Analog I/O
10	Motors with Binary Inputs
11	Motors with Analog Inputs
	Test #1

Course Content

• Lectures 12 - 24

Creating your own libraries

- LCD routines
- Matrix routines

Math & Random libraries

- What they include
- How to use their funcitons

Interrupts in Python

- Edge interrupts
- Timer interrupts

Controlling a DC motor

• Speed & angle control using interrupts

Reading Sensors

• Temperature, Current, Pulse, Wind, Pressure, etc.

12	LCD Graphic Display
13	Fun with LCD Graphics
14	Math and Random Library
15	Matrix Library
16	Edge Interrupts
17	Timer Interrupts
18	Speed Control of a DC Motor
19	Angle Control of a DC Motor
20	Text Files
21	Temperature Sensors
22	Current & Heart Rate Sensors
23	Wind, Pressure, Humidity Sensors
24	Acceleration & Light Sensors
	Test #2

Course Content

• Lectures 25-34

SCI & GPS

• Reading GPS sensors

NeoPixels and State Machines

• Pretty lights

I/O with Bluetooth

• send / receive data to your cell phone

WiFi in AP Mode

- set up a stand-alone WiFi network
- send / receive data

WiFi in Client Mode

- join an existing WiFi network
- send / receive data

25	SCI & GPS
26	NeoPixels
27	State Machines
28	Bluetooth
29	Bluetooth (cont'd)
30	Wi-Fi in AP Mode
31	WiFi & AP Tags
32	WiFi in Client Mode
33	WiFi & Client Tags
	Test #3

Course Information

Instructor: Jake Glower

Class Times Mo / We / Fr

Lab Times: Open Lab

Office Hours: Tu/Th 11am - noon

ECE 201 & Zoom

Text: Bison Academy (free!)

Bulletin Description:

• Specification, design, development, and rest of modern embedded systems using a high-level programming language. Prereq: ECE 376. F, S

Course Objectives:

By the end of the semester, students should:

- Be able to interface a microcontroller to binary inputs and outputs,
- Be able to interface a microcontroller to analog inputs and outputs,
- Be able to use a graphics display touch-screen for I/O,
- Be able to send/receive data to your cell phone using Bluetooth,
- Be able to access a WiFi network using a microcontroller, and
- Be able to do all of this using Python

Bison Academy

- www.BisonAcademy.com
- Where to access lecture notes, homework sets, etc. for ECE 476

BISON ACADEMY

ECE LABS

Advising Info

ECE Lab Supplies (new)

ECE 111: Intro to ECE

ECE 206: Circuits I

ECE 311: Circuits II

ECE 320: Digital Electronics

ECE 321: Analog Electronics

ECE 331: Energy Conversion

ECE 341: Random Processes

ECE 343: Signals and Systems

ECE 376: Embedded Systems

ECE 461: Controls Systems



Bison Academy: Syllabus

- Daily material (lecture topic in pdf format)
- Recorded lectures (YouTube)
- Sample Code (from lecture notes)
- Homework assignments

ECE 476: Advanced Embedded Systems

Syllabus: Fall 2024

Syllabus - HW & Solutions - Resources - Comments

	Date	Topic	Recorded Lecture YouTube PlayList	Code Used in lecture	Homework
М	Aug 26	Holiday			HW #1
W	Aug 28	1Introduction & Syllabus Slides #1	Video #1		
F	Aug 30	2 Thonny & MicroPython Slides #2	Video #2		
М	Sep 2	Holiday			HW #2
W	Sep 4	3 Loops & if-Statements Slides #3	Video #3	03 Timer2 Interrupts 03 For Loops 03 While Loops 03 d4 + d6	
F	Sep 6	4 Subroutines Slides #4	Video #4	04 Resistors 04 Convolution with Dice 04 Convolution with Polynomials	

Bison Academy: Homework and Solutions

Homework Assignments & Solutions from previous semesters

• Once the course runs for more than one semester

Tests and Solutions from Previous Semesters

- Good resource if you want sample problems to work on
- Code is usually removed (use sample code from the Syllabus as a starting point)

Fall 2021	Spring 2021	Fall 2020	Spring 2020	Fall 2019
1: PIC Background Solution #1 (pdf) Solution #1 (YouTube)	1: PIC Background solution#1	1: PIC Background Solution#1 (pdf) Solution#1 (YouTube)	1: PIC Background Solution#1	1: PIC Background Solution #1
2: PIC Assembler Solution #2 (pdf) Solution #2 (YouTube)	2: PIC Assembler Solution #2	2: PIC Assembler Solution #2 (pdf) Solution #2 (YouTube)	2: Assembler Solution #2	2: Assembler Solution #2
3: Binary I/O Solution #3 (pdf)	3: Binary I/O solution #3	3: Binary I/O Solution#3	3: Binary I/O solution#3	3: Binary I/O Solution #3
Test #1 Test #1 Solution (pdf) Test #1 Solution (YouTube)	Test #1 Test #1 Solution	Test #1 Test #1 Solutions	Test #1 Test#1 Solution	Test #1 Test #1 Solution
4: C-Coding Solution #4 (pdf) Solution #4 (YouTube)	4: C Coding Solution #4	4: C Coding Solution #4	4: C Coding Solution#4	4: C Coding Solution #4

Bison Academy: Best of 476

Most homework sets have four parts

- Requirements
- Hardware & Software
- Testing
- Validation & Demonstration

YouTube videos work well for validating and demonstrating your code works.

- The better videos are shared under "Best of 476" (with student permission)
- Good recruiting tool for ECE
- Good way to demonstrate your skills to future employers



Car Parking Sensor

Spring 2020

An ultrasonic range sensor det€
bar graph. When you're close e



Refrigerator Data Logger
Spring 2020
A PIC mircocontroller along will the time that the door remains



Automated Watering System
Spring 2020
A PIC mircontroller monitors the on to water the plants.

Lab Kits

- GeeekPi Pico Breadboard Kit Plus Version
- Motors, sensors, lights, etc.
- \$65 (cash of check pick up in room ECE 201)

Makes the class a lot more fun

• And understandable



Hy-Flex Model for ECE 476

Students are welcome to take this course however they like:

- In-Person:
- Live-Stream: on Zoom
- On-Line: YouTube recordings of lectures

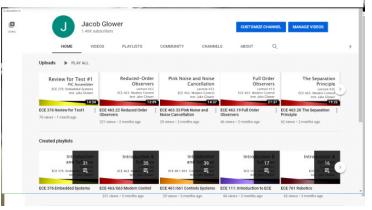
There is plenty of room, so you are welcome to attend each day however you like

• Whatever fits your schedule

Everyone is welcome to use the on-line resources on Bison Academy.







Evaluation Procedures and Grading Criteria

Grades will be the average of the following:

Midterms (x3)	Homework	Final Exam
75%	25%	none

Grades are rounded to the nearest 1%, with your final grade being

F	D	С	В	Α
59% or less	60% - 69%	70% - 79%	80% - 89%	90% or more

How to Get an A or B:

Keep up and do the homework.

- This class involves programming and interfacing hardware to your computer board.
- The only way I know to understand this interaction is to do it yourself.
- Sort of like weight lifting: watching someone else lift weights isn't the same as doing it yourself

Grades in this class are often bimodal:

- People who did the homework themselves tend to get either an A or a B.
- People who did not do the homework or copied tend to struggle to get a D.

Homework & Lab Projects

Groups of 1 or 2 allowed

• Only one homework set per group

Exams serve as a check that you're doing the homework

- If you do the homework, exams should be straight forward
- If you're giving moral support or copying code you found online, you'll probably struggle



Security Passcode Systems

Spring 2019

Using a numeric keypad, a passcoc buzzer sounds.



Mission Impossible Theme

Fall 2015

Using three PIC microcontrollers, th separate speakers.



Padlock Solver

Spring 2014

This embedded system will determine motor turns the lock and goes throutests the combination and a force s combination)

Open-Ended Assignments

Most homework sets are open-ended:

- You are free to specify what it is you're going to build and program
- Subject to it including things that we're covering that week, such as stepper motors

Each write-up includes four sections:

- Requirements What your device does
- Hardware & Software: Schematics & Code
- Test & Validation: Data to verify your design works (voltages, frequencies...)
- Demonstration: In-person or YouTube

This allows you to tailor your homework to your own interests



Reaction Test Game

Spring 2016

A game is set up using a PIC proc seconds later, a light turns on. Bc - the fastest player wins. The time LCD screen.



Scooby Doo Theme using Timer

Spring 2017

The theme from Scooby Doo is pleach note and Timer2 sets the du



Stepper Motor Tennis Game

Spring 2016

A game is programmed where tw the stepper motor reaches your s miss, you suffer humiliation. Time

Legal Stuff:

Attendance: According to NDSU Policy 333, attendance in classes is expected. How you attend is up to you (in-person, live-stream, online). Students are responsible for the material covered in class and in assignments regardless of their attendance. Note that all lecture notes, homework sets, and solutions are available on-line at www.BisonAcademy.com

Students with Special Needs: Any students with disabilities or other special needs, who need special accommodations in this course, are invited to share these concerns or requests with the instructor and contact the Disability Services Office (www.ndsu.edu/disabilityservices) as soon as possible.

Academic Honesty: The academic community is operated on the basis of honesty, integrity, and fair play. NDSU Policy 335: Code of Academic Responsibility and Conduct applies to cases in which cheating, plagiarism, or other academic misconduct have occurred in an instructional context. Students found guilty of academic misconduct are subject to penalties, up to and possibly including suspension and/or expulsion. Student academic misconduct records are maintained by the Office of Registration and Records. Informational resources about academic honesty for students and instructional staff members can be found at www.ndsu.edu/academichonesty.

Academic Honesty Defined: All written and oral presentations must "respect the intellectual rights of others. Statements lifted verbatim from publications must be cited as quotations. Ideas, summaries or paraphrased material, and other information taken from the literature must be properly referenced" (Guidelines for the Presentation of Disquisitions, NDSU Graduate School).

ECE Honor Code: On my honor I will not give nor receive unauthorized assistance in completing assignments and work submitted for review or assessment. I have to complete all my work with complete integrity.

Veterans and Student Soldiers: Veterans and student soldiers with special circumstances or who are activated are encouraged to notify the instructor in advance.